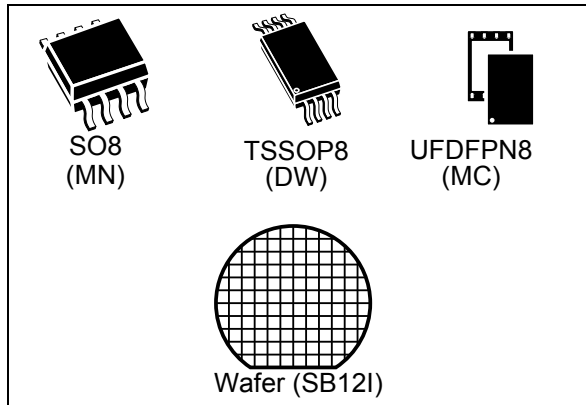

**Dynamic NFC/RFID tag IC with 64-Kbit EEPROM,
NFC Forum Type 4 Tag and I²C interface**

Datasheet - production data

**Package**

- 8-lead small-outline package (SO8) ECOPACK[®]2
- TSSOP8 ECOPACK[®]2
- UDFPN8 ECOPACK[®]2

Digital pad

- GPO: configurable General Purpose Output
- RF disable: activation/deactivation of RF commands

Description

The M24SR64-Y device is a dynamic NFC/RFID tag IC with a dual interface. It embeds an EEPROM memory. It can be operated from an I²C interface or by a 13.56 MHz RFID reader or an NFC phone.

The I²C interface uses a two-wire serial interface, consisting of a bidirectional data line and a clock line. It behaves as a slave in the I²C protocol.

The RF protocol is compatible with ISO/IEC 14443 Type A and NFC Forum Type 4 Tag.

Features**I²C interface**

- Two-wire I²C serial interface supports 1 MHz protocol
- Single supply voltage: 2.7 V to 5.5 V

Contactless interface

- NFC Forum Type 4 Tag
- ISO/IEC 14443 Type A
- 106 Kbps data rate
- Internal tuning capacitance: 25 pF

Memory

- 8-Kbyte (64-kbit) EEPROM
- Support of NDEF data structure
- Data retention: 200 years
- Endurance: 1 million erase-write cycles
- Read up to 246 bytes in a single command
- Write up to 246 bytes in a single command
- 7 bytes unique identifier (UID)
- 128 bits passwords protection

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1 Functional description

The M24SR64-Y device is a dynamic NFC/RFID tag that can be accessed either from the I²C or the RF interface. The RF and I²C host can read or write to the same memory, that is why only one host can communicate at a time with the M24SR64-Y. The management of the interface selection is controlled by the M24SR64-Y device itself.

The RF interface is based on the ISO/IEC 14443 Type A standard. The M24SR64-Y is compatible with the NFC Forum Type 4 Tag specifications and supports all corresponding commands.

The I²C interface uses a two-wire serial interface consisting of a bidirectional data line and a clock line. The devices carry a built-in 4-bit device type identifier code in accordance with the I²C bus definition.

The device behaves as a slave in the I²C protocol.

Figure 1 displays the block diagram of the M24SR64-Y device.

Figure 1. M24SR64-Y block diagram

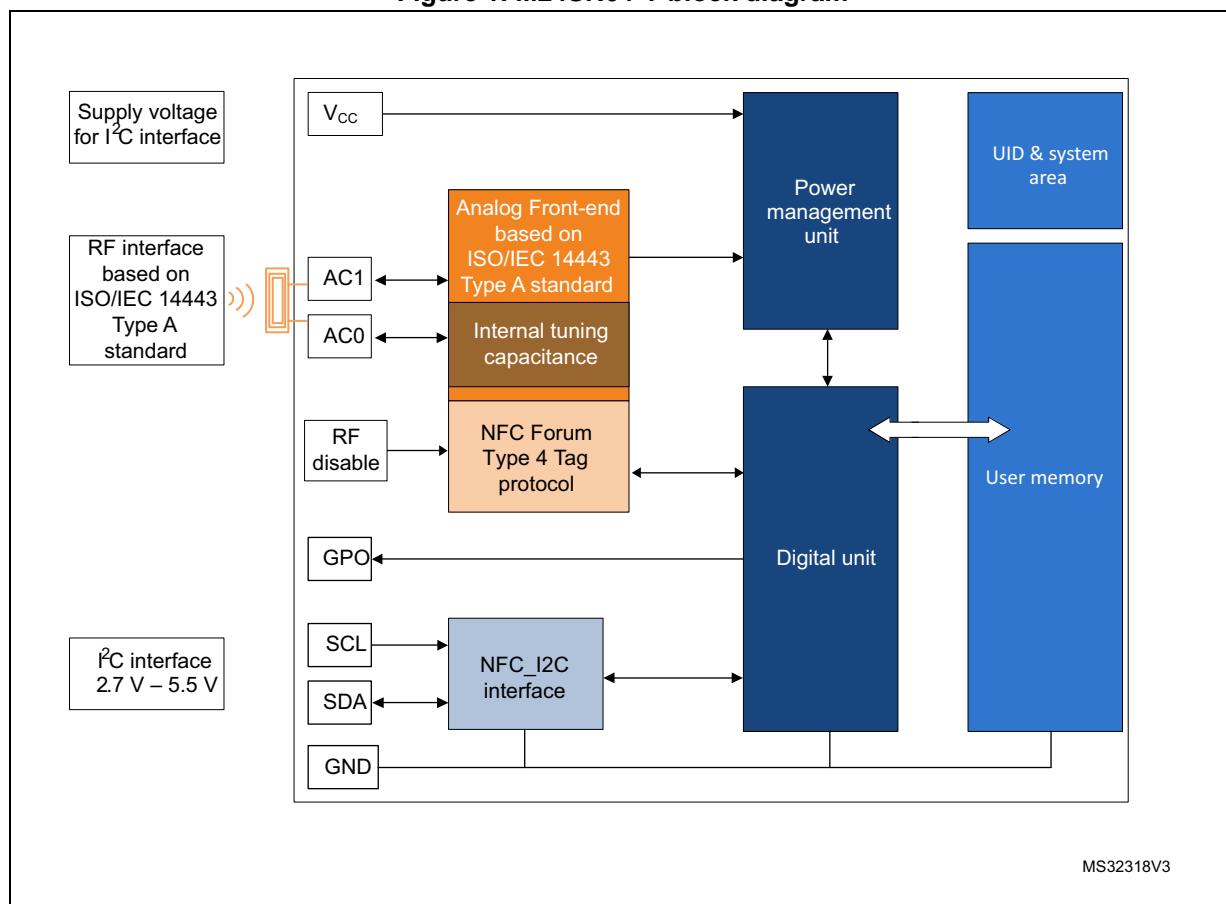


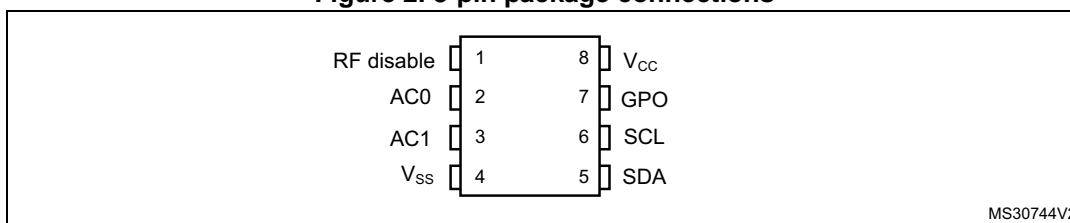
Table 1. Signal names

| Signal name | Function | Direction |
|-----------------|---|-------------------|
| SDA | Serial data | I/O |
| SCL | Serial clock | Input |
| AC0, AC1 | Antenna coils | - |
| V _{CC} | Supply voltage | - |
| V _{SS} | Ground | - |
| GPO | Interrupt output ⁽¹⁾ | Open drain output |
| RF disable | Disable the RF communication ⁽²⁾ | Input |

1. An external pull-up > 4.7 kΩ is required.

2. An external pull-down is required when the voltage on V_{CC} is above its POR level.

Figure 2. 8-pin package connections



1. See Package mechanical data section for package dimensions, and how to identify pin 1.

1.1 Functional modes

The M24SR64-Y has two functional modes available. The difference between the modes lies in the power supply source (see [Table 2](#)).

Table 2. Functional modes

| Modes | Supply source | Comments |
|-----------------------|-----------------------------|---|
| I ² C mode | V _{CC} | The I ² C interface is available |
| Tag mode | RF field only | The I ² C interface is disconnected |
| Dual interface mode | RF field or V _{CC} | Both I ² C and RF interfaces are available |

1.1.1 I²C mode

M24SR64-Y is powered by V_{CC}. The I²C interface is connected to the M24SR64-Y. The I²C host can communicate with the M24SR64-Y device.

1.1.2 Tag mode

The M24SR64-Y is supplied by the RF field and can communicate with an RF host (RFID reader or an NFC phone). The User memory can only be accessed by the RF commands.

1.1.3 Dual interface mode

Both interfaces, RF and I²C, are connected to the M24SR64-Y and both RF or I²C host can communicate with the M24SR64-Y device. The power supply and the access management are carried out by the M24SR64-Y itself. For further details, please refer to the token mechanism chapter.

2 Signal descriptions

2.1 Serial clock (SCL)

This input signal is used to strobe all data in and out of the device. In applications where this signal is used by slave devices to synchronize the bus to a slower clock, the bus master must have an open drain output, and a pull-up resistor must be connected from Serial clock (SCL) to V_{CC} . (Figure 17 indicates how the value of the pull-up resistor can be calculated).

In most applications, though, this method of synchronization is not employed, and so the pull-up resistor is not necessary, provided that the bus master has a push-pull (rather than open drain) output.

2.2 Serial data (SDA)

This bidirectional signal is used to transfer data in or out of the device. It is an open drain output that may be wire-OR'ed with other open drain or open collector signals on the bus. A pull-up resistor must be connected from Serial data (SDA) to V_{CC} . (Figure 17 indicates how the value of the pull-up resistor can be calculated).

2.3 Antenna coil (AC0, AC1)

These inputs are used to connect the device to an external coil exclusively. It is advised not to connect any other DC or AC path to AC0 or AC1.

When correctly tuned, the coil is used to access the device using NFC Forum Type 4 commands.

2.4 Ground (V_{SS})

V_{SS} , when connected, is the reference for the V_{CC} supply voltage for all pads, even AC0 and AC1.

2.5 Supply voltage (V_{CC})

This pin can be connected to an external DC supply voltage.

Note: An internal voltage regulator allows the external voltage applied on V_{CC} to supply the M24SR64-Y.

2.5.1 Operating supply voltage V_{CC}

Prior to selecting the M24SR64-Y and issuing instructions to it, a valid and stable V_{CC} voltage within the specified [$V_{CC}(\min)$, $V_{CC}(\max)$] range must be applied. To maintain a stable DC supply voltage, it is recommended to decouple the V_{CC} line with suitable capacitors (usually of the order of 10 nF and 100 pF) close to the V_{CC}/V_{SS} package pins.

This voltage must remain stable and valid until the end of the transmission of the instruction and, for a writing instruction (UpdateBinary, ChangeReferenceData,

EnableVerificationRequirement, DisableVerificationRequirement, EnablePermanentState, DisablePermanentState, until the completion of the internal I²C write cycle (t_W).

2.5.2 Power-up conditions

When the power supply is turned on, V_{CC} rises from V_{SS} to V_{CC} . The V_{CC} rise time must not vary faster than $1V/\mu s$.

2.5.3 Device reset in I²C mode

In order to prevent inadvertent write operations during power-up, a power-on reset (POR) circuit is included. At power-up (continuous rise of V_{CC}), the M24SR64-Y does not respond to any I²C instruction until V_{CC} has reached the power-on reset threshold voltage (this threshold is lower than the minimum V_{CC} operating voltage defined). When V_{CC} passes over the POR threshold, the device is reset and enters the Standby power mode. However, the device must not be accessed until V_{CC} has reached a valid and stable V_{CC} voltage within the specified [$V_{CC}(\min)$, $V_{CC}(\max)$] range.

In a similar way, during power-down (continuous decrease in V_{CC}), as soon as V_{CC} drops below the power-on reset threshold voltage, the M24SR64-Y stops responding to any instruction sent to it.

2.5.4 Power-down conditions

During power-down (continuous decay of V_{CC}), the M24SR64-Y must be in Standby power mode (mode reached after decoding a Stop condition, assuming that there is no internal operation in progress).

2.6 RF disable

This input signal is used to disable the RF communication. When the voltage on the V_{CC} pin is below the POR level or not connected, an internal pull-down resistor is connected on this pad. Thus, the RF disable pad is maintained to the low level and the RF analog front end is activated. When the voltage on the V_{CC} pin is higher than the POR level, the I²C host shall set this pin to enable or disable the RF communication. In Dual interface mode, RF disable must not be left floating.

2.7 General purpose output (GPO)

The GPO pad is an open drain pad and an external pull-up resistor shall be connected to it. This pad is a configurable output signal. On delivery, GPO is configured as Session opened. Its behavior is consistent with the I²C or RF session activated and with the mode chosen by the user. The GPO pad is enable when an RF or an I²C session is open. When neither an RF nor an I²C session is open, the GPO is high impedance.

The user can select one of these configurations^(a):

- SessionOpen: an RF or I²C session is ongoing.
- MIP (NDEF Message updating In Progress): the RF host is writing an NDEF length different from 0x0000. This mode can be used to detect when the RF host changes the NDEF message as defined by the NFC Forum.
- WIP (Writing In Progress): the M24SR64-Y is executing a writing operation.
- INT (interrupt): the I²C or RF host can force the M24SR64-Y to send a negative pulse on the GPO pin.
- I²C ready response: an I²C response is ready to be read by the I²C host.
- State mode: the I²C or RF host can control the state of the GPO pad during the RF session.
- RF busy: an RF host is communicating with the M24SR64-Y.

2.7.1 Session Open configuration (GPO field = 0xX1 or 0x1X)

When the GPO is configured as "Session Open", it goes to the Low state when an RF or I²C session is ongoing (see [Figure 2.7.2](#)).

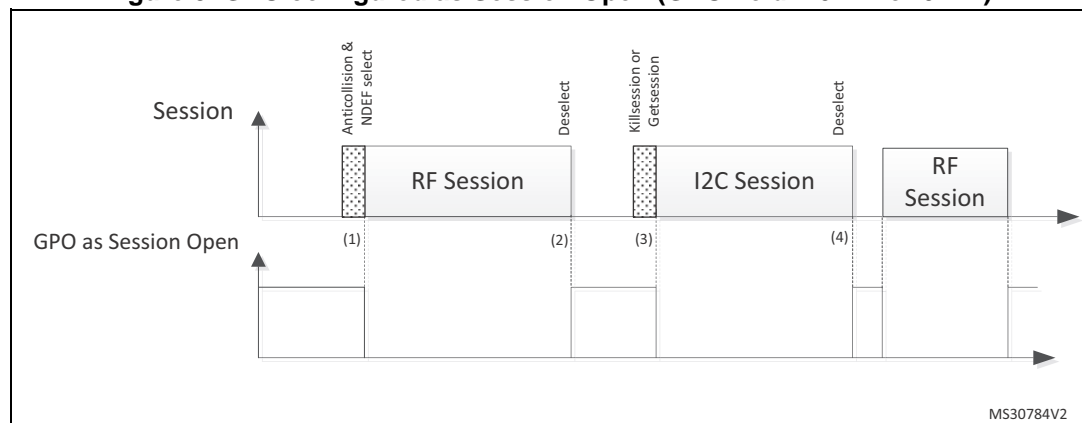
An RF session is taken when M24SR64-Y receives a valid Select Application. The session is released after M24SR64-Y has received a valid Deselect command, if M24SR64-Y has received a Kill RF session command in I²C or when the RF field became OFF.

An I²C session is taken when M24SR64-Y receives a valid Get session command or a valid Kill RF session command. The session is released after M24SR64-Y has received a valid Deselect command or after a Power Off.

GPO is driven low after a delay (1) or (3) when the session is open.

GPO is released after a delay (2) or (4) when the session is released.

Figure 3. GPO configured as Session Open (GPO field = 0xX1 or 0x1X)



1. CmdEOFToGPlow (RF command End of frame to GPORF Session pad low)
2. CmdEOFToGPHZ (RF command End of frame to GPORF Session pad HZ)
3. CmdSTPtoGPlow (I2C command stop to GPO low)
4. AnswerlLBtoGPHZ (I2C answer last bit of last byte to GPO HZ)

a. See [Table 78](#) for more details.

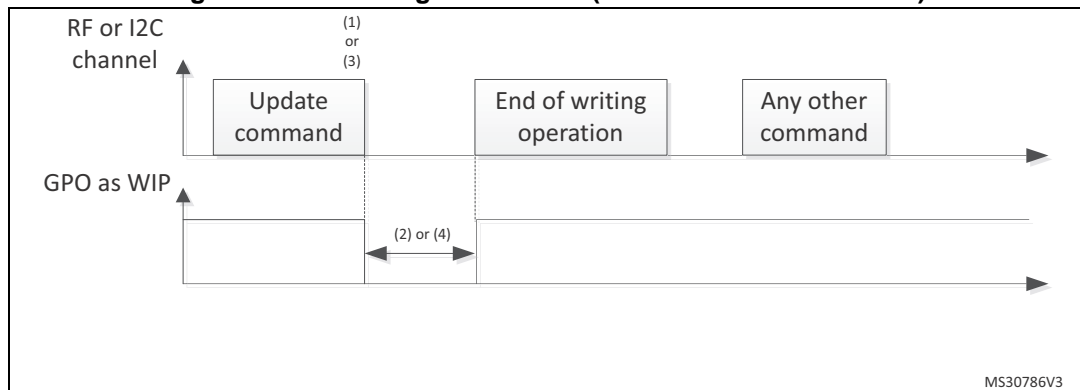
2.7.2 WIP Writing in Progress configuration (GPO field = 0xX2 or 0x2X)

When the GPO is configured as "WIP", it goes to the Low state during an I²C or RF writing operation.

During an RF or I²C session, when M24SR64-Y updates a file, GPO is driven low after a delay (1) or (3) following the beginning of the correspondent UpdateBinary command execution.

GPO will remain low during the writing time (2) or (4), before being released.

Figure 4. GPO configured as WIP (GPO field = 0xX2 or 0x2X)



MS30786V3

1. CmdSTPtoGPlow (I2C Command Stop to GPO low)
2. Writing time duration
3. CmdEOFtoGPlow (RF Command End of frame to GPO low)
4. Writing time duration

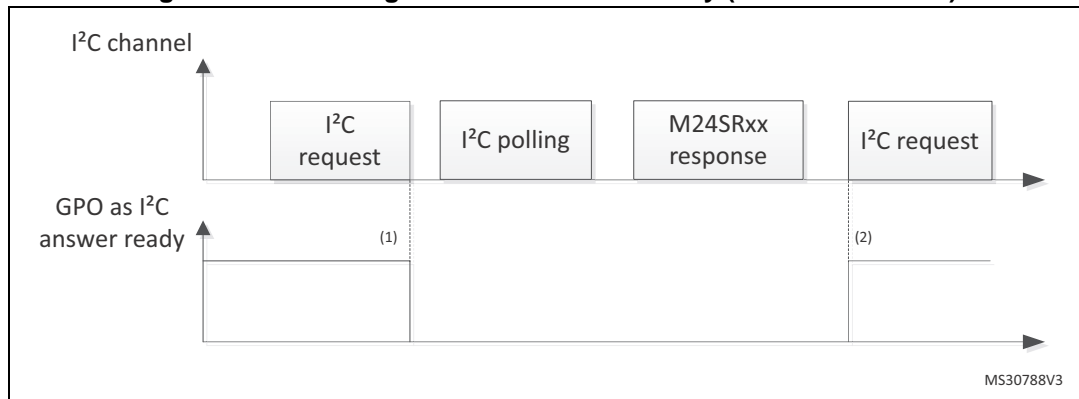
2.7.3 I²C answer ready configuration (GPO field = 0xX3)

When the GPO is configured as I²C answer ready, it goes to the Low state when the M24SR64-Y has finished to treat the I²C command and is ready to send the I²C response.

During an I²C session, after receiving a valid I²C command, GPO pin is driven low after a delay (1) when M24SR64-Y is ready to deliver a response on the I²C bus.

GPO is released after (2) when M24SR64-Y receives a new command.

Figure 5. GPO configured as I²C answer ready (GPO field = 0xX3)



1. CmdSTPtoGPlow (I2C command Stop to GPO low)
2. After NewCmdlbFB (new I2C command last bit of first byte)
or
after AnswerlbFB (I2C answer last bit of first byte)

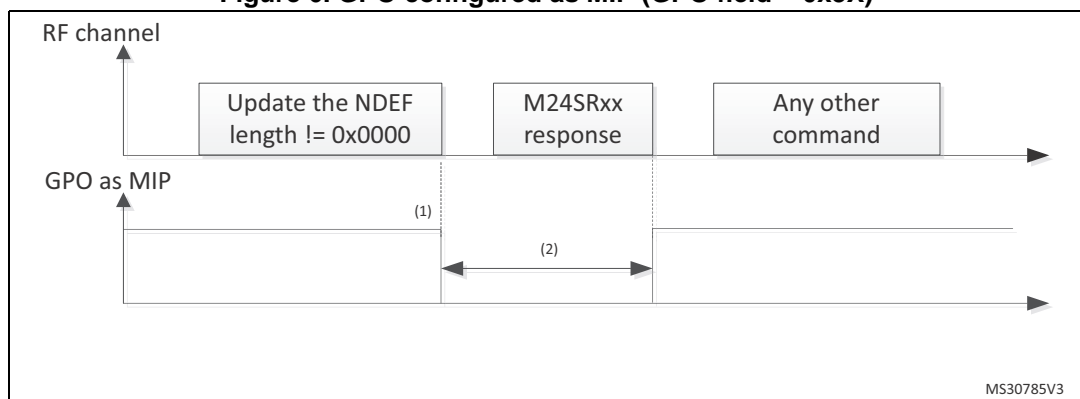
2.7.4 MIP NDEF Message writing in Progress configuration (GPO field = 0x3X)

When the GPO is configured as MIP, its state goes to the low state when the RF host writes the NDEF length to another value than 0x0000.

During an RF session, when M24SR64-Y changes an NDEF file and updates the NDEF length with a value different from 0x0000, GPO is driven low after a delay (1) following the beginning of the correspondent UpdateBinary command execution.

GPO will remain low during the writing time (2), before being released.

Figure 6. GPO configured as MIP (GPO field = 0x3X)



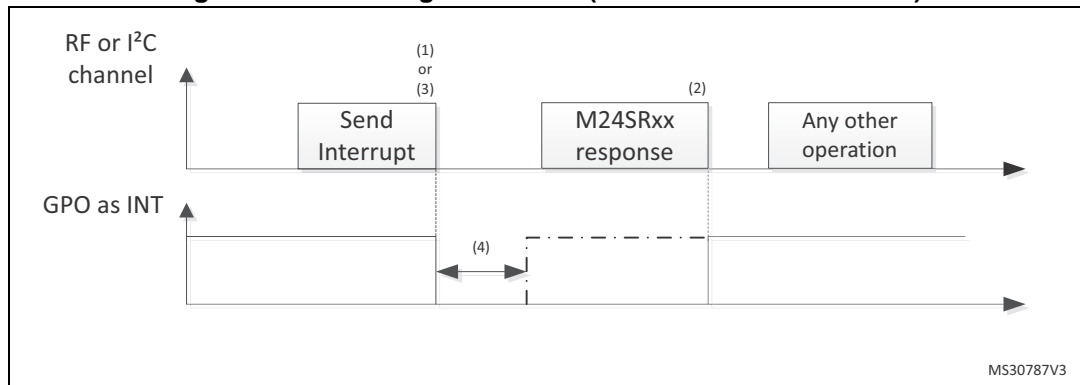
1. CmdEOFToGPIow (RF command End of frame to GPO low)
2. Writing time duration

2.7.5 INT Interrupt configuration (GPO field = 0xX4 or 0x4X)

The I²C or RF host can send a negative pulse on the GPO pad. The GPO pad goes to the low state at the end of the command and goes to the high state at the end of the M24SR64-Y response.

During an RF or I²C session, when M24SR64-Y receives a valid Interrupt command, M24SR64-Y GPO pin is driven low after (1) or (3) for a duration of (4) in RF, or after responding in I2C (2). Then GPO pin is released.

Figure 7. GPO configured as INT (GPO field = 0xX4 or 0x4X)



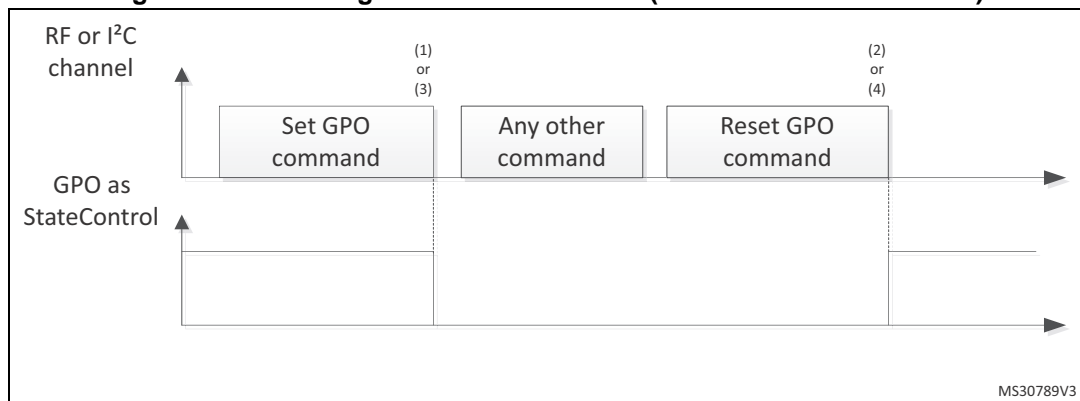
1. CmdSTPtoGPlow (I2C command Stop to GPO low)
2. After NewCmdIbFB (new I2C command last bit of first byte)
or
after AnswerIbFB (I2C answer last bit of first byte)
3. CmdEOFtoGPlow (RF command End of frame to GPO low)
4. GPO pulse duration

2.7.6 State Control configuration (GPO field = 0xX5 or 0x5X)

When the GPO is configured as State Control, the I²C or RF host can control the state of the GPO by sending a dedicated command.

During an RF or I²C session, the M24SR64-Y can control the GPO pin. After receiving a valid Set GPO command, GPO pin is driven low after a delay (1) or (3). GPO will be released after a valid Reset command or after a Power off.

Figure 8. GPO configured as State Control (GPO field = 0xX5 or 0x5X)



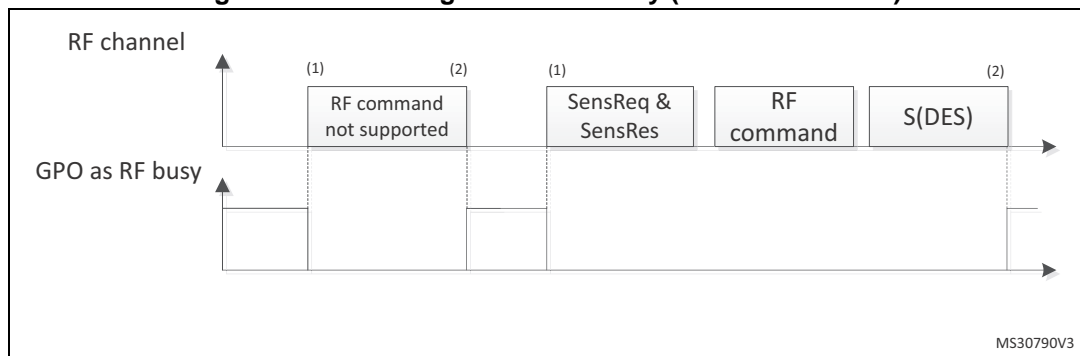
1. CmdSTPtoGPlow (I2C Set GPO command Stop to GPO low)
2. CmdSTPtoGPHZ (I2C Reset GPO command Stop to GPO HZ)
3. CmdEOFtoGPlow (RF Set GPO command End of frame to GPO low)
4. CmdEOFtoGPHZ (RF Reset GPO command End of frame to GPO HZ)

2.7.7 RF busy configuration (GPO field = 0x6X)

When the GPO is configured as RF busy, the GPO goes to the low state when the M24SR64-Y is processing an RF command or when an RF session is ongoing.

When an RF field is present, GPO is driven low after a delay (1) when M24SR64-Y detects the first command. If the RF session is ongoing and M24SR64-Y receives a not-supported command, GPO remains low. It will be released only at the end of the RF session, after (2).

Figure 9. GPO configured as RF busy (GPO field = 0x6X)



1. CmdSOFtoGPlow (RF command Start of frame to GPO low)
2. CmdEOFtoGPHZ (RF command End of frame to GPO HZ)

3 M24SR64-Y memory management

3.1 Memory structure

The M24SR64-Y supports the NDEF Tag Application as defined in the NFC Forum Type 4 Tag. The M24SR64-Y is composed of three files:

- One Capability Container file
- One NDEF file
- One System file: this is an ST-proprietary file

The System file contains some information on the configuration of the M24SR64-Y device. The CC file gives some information about the M24SR64-Y itself and the NDEF file. The NDEF file contains the User data.

3.1.1 File identifier

The file identifier is the value used in the Select command to select a file.

Table 3. File identifier

| File identifier | Meaning |
|-----------------|-------------|
| 0xE101 | System file |
| 0xE103 | CC file |
| 0x0001 | NDEF file |

3.1.2 CC file layout

The CC file gives some information about the M24SR64-Y and the NDEF file. This file is a read-only file for the RF or I²C host and cannot be modified by issuing a write command.

The T field, Read Access and Write Access fields can be changed by the RF or I²C host by issuing a specific process (refer to [Section 8: Functional procedures](#)).

Table 4. CC file layout for 1 NDEF file

| File offset | Meaning | Value | Comments |
|-------------|---|---------------------|------------------------|
| 0x0000 | Number of bytes of CC file | 0x000F | 15 bytes |
| 0x0002 | Mapping version ⁽¹⁾ | 0x20 or 0x10 | V 2.0 or V 1.0 |
| 0x0003 | Maximum number of bytes that can be read | 0x00F6 | 246 bytes |
| 0x0005 | Maximum number of bytes that can be written | 0x00F6 | 246 bytes |
| 0x0007 | NDEF file control TLV | 0x04 ⁽²⁾ | T field |
| 0x0008 | | 0x06 | L field |
| 0x0009 | | 0x0001 | FileID |
| 0x000B | | 0x2000 | Maximum NDEF file size |
| 0x000D | | 0x00 ⁽²⁾ | Read access |
| 0x000E | | 0x00 ⁽²⁾ | Write access |

1. According to the reader.

2. Delivery state.

3.1.3 NDEF file layout

The NDEF file contains the NDEF message which contains the User data. The RF host or the I²C host can read and write data inside the file. The first two bytes named NDEF Message Length define the size of the NDEF message. The NDEF Message Length shall be managed by the application and the M24SR64-Y device does not check if its value is relevant vs the data written by the RF or I²C host. The M24SR64-Y device uses the NDEF Message Length, e. g. the standard read can be processed only inside the NDEF message; otherwise, the M24SR64-Y device returns an error code. For more details about the read command, refer to [Section 5.6.7: ReadBinary command](#).

Table 5. NDEF file layout

| File offset | Byte 0 | Byte 1 | Byte 2 | Byte 3 |
|-------------|---------------------|-----------|-----------|-----------|
| 0x0000 | NDEF message length | | User data | User data |
| 0x0004 | User data | User data | User data | User data |
| ... | ... | ... | ... | ... |
| ... | ... | ... | ... | ... |
| ... | ... | ... | ... | ... |
| 0x1FFF | ... | ... | ... | User data |

3.1.4 System file layout

The system file specifies the configuration of the M24SR64-Y. [Table 6](#) lists the different fields.

Table 6. Field list

| File offset | Field name | Number of bytes | Read access | Write access | Delivery state ⁽¹⁾ |
|-------------|---------------------------|-----------------|------------------------|---------------------------------|---|
| 0x0000 | Length system file | 2 | I ² C or RF | - | 0x0012 |
| 0x0002 | I ² C protect | 1 | I ² C or RF | I ² C ⁽²⁾ | 0x01 |
| 0x0003 | I ² C watchdog | 1 | I ² C or RF | I ² C ⁽²⁾ | 0x00 |
| 0x0004 | GPO | 1 | I ² C or RF | I ² C ⁽²⁾ | 0x11 |
| 0x0005 | ST reserved | 1 | I ² C or RF | I ² C ⁽²⁾ | 0x00 |
| 0x0006 | RF enable | 1 | I ² C or RF | I ² C ⁽²⁾ | 0x01 |
| 0x0007 | NDEF File number (RFU) | 1 | I ² C or RF | none | 0x00 |
| 0x0008 | UID | 7 | I ² C or RF | none | 0x0284 xx xx xx xx xx ⁽³⁾ |
| 0x000F | Memory Size | 2 | I ² C or RF | none | 0x1FFF |
| 0x0011 | Product Code | 1 | I ² C or RF | none | 0x84 |

1. The delivery state for all passwords = 0x00000000000000000000000000000000.

2. The access is granted when the field I²C protect is set to the state Unprotected or when the right I²C password was correctly received (see [Section 3.5: I²C password](#)).

3. x values are defined by ST to insure UID unicity.

Table 7. Details about the GPO field

| File offset | b7 | b6-b4 | b3 | b2-b0 |
|---|-----|-------|----|-------|
| 0x0004 | RFU | | | |
| RFU | | | | |
| When an RF session is open: | | | | |
| 0b000: High impedance | | | | |
| 0b001: Session opened | | | | |
| 0b010: WIP | | | | |
| 0b011: MIP | | | | |
| 0b100: Interrupt | | | | |
| 0b101: State Control | | | | |
| 0b110: RF Busy | | | | |
| 0b111: RFU | | | | |
| RFU | | | | |
| When an I ² C session is open: | | | | |
| 0b000: High impedance | | | | |
| 0b001: Session opened | | | | |
| 0b010: WIP | | | | |
| 0b011: I ² C Answer Ready | | | | |
| 0b100: Interrupt | | | | |
| 0b101: State Control | | | | |
| 0b110: RFU | | | | |
| 0b111: RFU | | | | |

Table 8. Details about the RF Session field

| File offset | b7 | b6-b4 | b3-b0 | |
|--|----|-------|-------|--|
| 0x0004 | | | | |
| RFU | | | | |
| When an RF session is open: 0b001: Session opened | | | | |
| RFU | | | | |

[Table 9](#) gives some details about the ST reserved field.

Table 9. Details about the ST reserved field

| File offset | b7-b0 |
|-------------|-------|
| 0x0005 | |
| 0x00 | |

[Table 10](#) gives some details about the RF enable field.

Table 10. Details about the RF enable field

| File offset | b7 | b6-b4 | b3 | b2-b1 | b0 |
|--|---|-------|----|-------|----|
| 0x0006 | 0: the RF field is off ⁽¹⁾ 1: the RF field is on ⁽¹⁾ | | | | |
| RFU | | | | | |
| 0: the RF disable pad is at low state ⁽¹⁾ 1: the RF disable pad is at high state ⁽¹⁾ | | | | | |
| RFU | | | | | |
| 0: the M24SR64-Y does not decode the command received from the RF interface 1: the M24SR64-Y decodes the command received from the RF interface | | | | | |

1. this field is written by the M24SR64-Y.

3.2 Read and write access rights to the memory

An NDEF file can be locked for read or write accesses. It is also protected by a 128-bit password that the host shall present before accessing the NDEF file. There are two 128-bit passwords, one for the read access and the other one for the write access.

An NDEF file can be permanently locked for read or write accesses. Thus, the host cannot access the NDEF file.

The read password shall be sent to the M24SR64-Y device before reading a read-locked NDEF file.

The write password shall be present on the M24SR64-Y device before writing a write-locked NDEF file. The write password shall be sent to change the read or write access. The read or write access right is defined for the NDEF file.

3.2.1 State of the Read and Write access rights

Two bytes in the CC file are used to define the Read and Write access rights to the NDEF file. For more details, refer to [Section 3.1.2: CC file layout](#).

Table 11. Read access right

| Value | Meaning |
|-------|----------------------------------|
| 0x00 | Read access without any security |
| 0x80 | Locked ⁽¹⁾ |
| 0xFE | Read not authorized |

1. The read password shall be sent before reading in the NDEF file.

Table 12. Write access right

| Value | Meaning |
|-------|-----------------------------------|
| 0x00 | Write access without any security |
| 0x80 | Locked ⁽¹⁾ |
| 0xFF | Write not authorized |

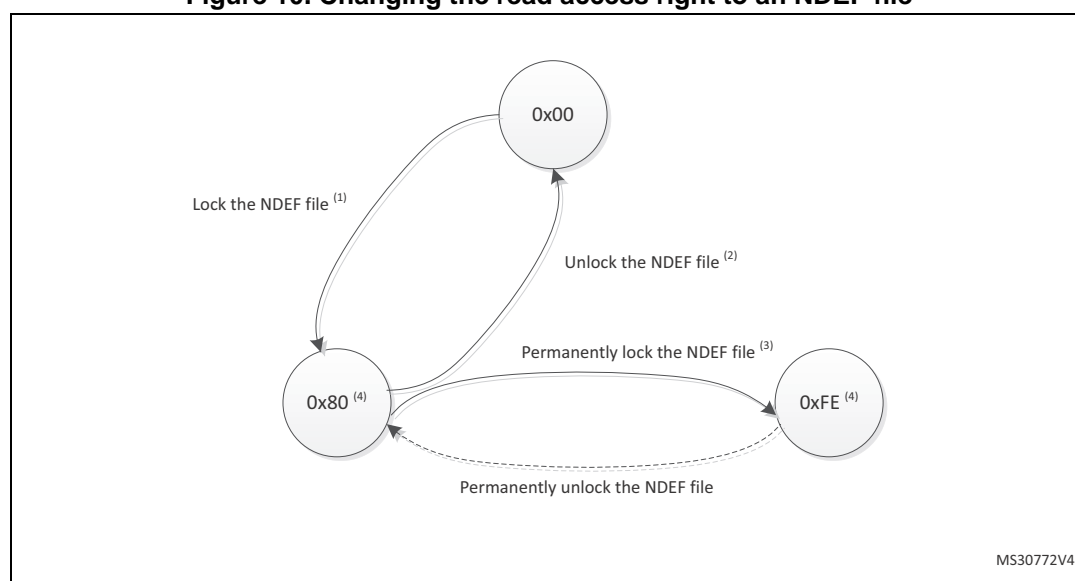
1. The write password shall be sent before writing in the NDEF file.

The state 0xFF and 0xFE cannot be changed by using the Read or Write passwords.

3.2.2 Changing the read access right to NDEF files

The state diagram on [Figure 1](#) shows how to change the access right to read an NDEF file.

Figure 10. Changing the read access right to an NDEF file

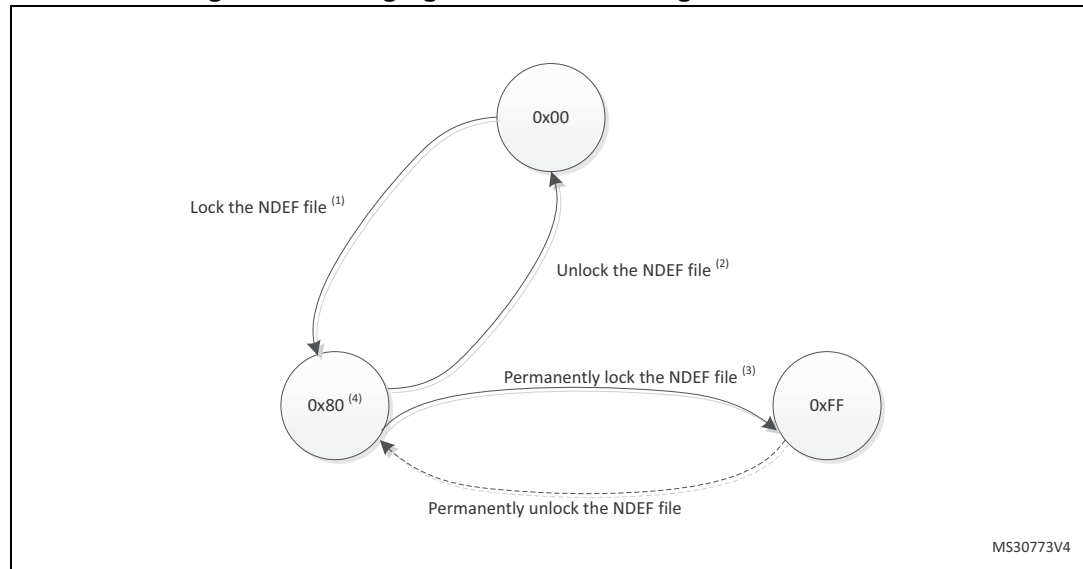


1. See the procedure to lock the read access ([Section 8.4: Locking an NDEF file](#)).
2. See the procedure to unlock the read access ([Section 8.5: Unlocking an NDEF file](#)).
3. See the procedure to permanently lock the read access ([Section 8.6: Reaching the read-only state for an NDEF file](#)).
4. Proprietary state, not defined by NFC Forum Type 4 Tag.

3.2.3 Changing the write access right to NDEF files

The state diagram on [Figure 1](#) shows how to change the write access right to an NDEF file.

Figure 11. Changing the write access right to an NDEF file



1. See the procedure to lock the write access.
2. See the procedure to unlock the write access.
3. See the procedure to permanently lock the write access ([Section 8.6: Reaching the read-only state for an NDEF file](#)).
4. Proprietary state, not defined by NFC Forum Type 4 Tag.

3.3 Access right life time

The access right life time is validated while the NDEF file is selected or until the end of the RF or I²C session. Once the read or write access right is granted, the host can send one or more ReadBinary or UpdateBinary commands.

At the end of a session or when the host selects another file, the read and write access rights are initialized.

3.4 NDEF file passwords

The NDEF file passwords protect the read or write access from an RF or I²C interface from/to an NDEF file.

Two NDEF file passwords are available for each NDEF file:

- Read password
- Write password

The length of a password is 128 bits (16 bytes).

3.5 I²C password

The I²C password can be sent only by the I²C host. It activates the SuperUser rights. The I²C host with the SuperUser rights can:

- Access the NDEF file regardless of the right access and without sending the NDEF file passwords.
- Change the access rights regardless of the current state.

The length of the I²C password is 128 bits (16 bytes).

3.5.1 I²C password and I²C protect field of the System file

The I²C protect field in the system file can be set to:

- 0x00: the I²C host has the SuperUser right access without sending the I²C password
- 0x01: the I²C host has the SuperUser right access after sending the I²C password

For more details about the system file layout, refer to [Section 3.1.4: System file layout](#).

4 Communication mechanism

This chapter describes the principle of communication between an RF or an I²C host and the M24SR64-Y device.

4.1 Master and slave

The M24SR64-Y acts as a slave device on either the I²C-bus or the RF channel and therefore waits for a command from the I²C master or the RF host before sending its response.

The RF host shall generate the RF field and the RF commands.

The I²C host shall supply the M24SR64-Y through the V_{CC} pin and shall generate the I²C clock on the SCL pad.

4.2 M24SR64-Y session mechanism

The M24SR64-Y is a dynamic NFC/RFID tag which can be accessed either from the RF or I²C interface. The M24SR64-Y implements a token system. This token has two possible values, RF or I²C. When the token exists and is assigned to one interface (RF or I²C), the M24SR64-Y cannot communicate with the other host.

4.2.1 RF token

The token is given to the RF interface once the anticollision is done. The release condition can be either an RF field cut-off, or the reception of the command deselect, or when the I²C host sends the KillRFsession.

4.2.2 I²C token

The token is given to the I²C interface when the I²C host has sent the correct device Select. The release condition can be either a power down condition on V_{CC} pin or the reception of a command deselect from the I²C host, after which M24SR64-Y goes in Standby power mode.

5 I²C and RF command sets

The command sets of the M24SR64-Y can be split in different command families. Most commands are common between the RF and the I²C interface. Some commands are specific to the RF interface and some others are specific to the I²C interface. This section describes the M24SR64-Y command sets that can be issued by the RF or the I²C host.

There are three command families:

- the NFC Forum Type 4 Tag command set
- the ISO/IEC 7816-4 command set
- the proprietary command set

The NFC Forum Type 4 Tag command set and the ISO/IEC 7816-4 command set use the I-Block format. For more details about the I-Block format, refer to [Section 5.2: I-Block format](#).

Two other command formats exist:

- the commands using the R-Block format
- the commands using the S-Block format

For more details about these formats, refer to the corresponding sections: [Section 5.3: R-Block format](#) and [Section 5.4: S-Block format](#).

This section gives a brief description of the RF and I²C host common commands. The format of these command sets is the I-Block format.

[Table 13](#) lists the RF and I²C command sets.

Table 13. RF and I²C command sets

| Family command set | Command name | Class byte | Instruction code | Brief description |
|----------------------|--------------------------------|------------|------------------|--|
| NFC Forum Type 4 Tag | NDEF Tag Application Select | 0x00 | 0xA4 | NDEF Tag Application Select |
| | CC select | 0x00 | 0xA4 | Select the CC file |
| | NDEF select | 0x00 | 0xA4 | Select the NDEF file |
| | System select | 0x00 | 0xA4 | Select the system file |
| | ReadBinary | 0x00 | 0xB0 | Read data from file |
| | UpdateBinary | 0x00 | 0xD6 | Write or erase data to a NDEF file |
| ISO/IEC 7816-4 | Verify | 0x00 | 0x20 | Checks the right access of a NDEF file or sends a password |
| | ChangeReferenceData | 0x00 | 0x24 | Change a Read or write password |
| | EnableVerificationRequirement | 0x00 | 0x28 | Activate the password security |
| | DisableVerificationRequirement | 0x00 | 0x26 | Disable the password security |

Table 13. RF and I²C command sets (continued)

| Family command set | Command name | Class byte | Instruction code | Brief description |
|--------------------|----------------------|------------|------------------|--|
| ST Proprietary | EnablePermanentState | 0xA2 | 0x28 | Enables the Read Only or Write Only security state |
| ST Proprietary | ExtendedReadBinary | 0xA2 | 0xB0 | Read data from file |

5.1 Structure of the command sets

The exchange of data between the RF or the I²C host and the M24SR64-Y uses three kinds of data formats, called blocks:

- I-Block: to exchange the command and the response
- R-Block: to exchange positive or negative acknowledgement
- S-Block: to use either the Deselect command or the Frame Waiting eXtension (WTX) command or response

This section describes the structure of the I-Block, R-block and S-Block. This format is used for the application command set.

5.2 I-Block format

The I-Block is used to exchange data between the RF or the I²C host and the M24SR64-Y. It is composed of three fields. [Table 14](#) details the I-Block format.

Table 14. I-Block format

| Name | SoD | | Payload | EoD |
|--|--------|--------|----------------|---------|
| | PCB | DID | 0 | CRC |
| Length | 1 byte | 1 byte | 1 to 251 bytes | 2 bytes |
| PCB field | | | | |
| DID field (optional) | | | | |
| RF or I ² C host to M24SR64-Y: C-APDU M24SR64-Y to RF or I ² C host: R-APDU | | | | |
| 2 CRC bytes | | | | |

Table 15. PCB field of the I-Block format

| | b7-b6 | b5 | b4 | b3 | b2 | b1 | b0 |
|--------------------------|-------|----|----|----|----|----|----|
| | 0b00 | 0 | 0 | X | 0 | 1 | X |
| I-Block | | | | | | | |
| RFU | | | | | | | |
| Must be set to 0 | | | | | | | |
| DID field, if bit is set | | | | | | | |
| Must be set to 0 | | | | | | | |
| Must be set to 1 | | | | | | | |
| Block number | | | | | | | |

When the RF or I²C host sends a command to the M24SR64-Y the format of the payload is the C-APDU.

When the M24SR64-Y sends a command to the RF or I²C host, the format of the payload is the R-APDU.

5.2.1 C-APDU: payload format of a command

The C-APDU format is used by the RF or the I²C host to send a command to the M24SR64-Y. [Table 16](#) describes its format.

Table 16. C-APDU format

| Name | Payload field | | | | | | |
|--|---------------|--------|--------|--------|--------|---------|--------|
| | CLA | INS | P1 | P2 | LC | Data | Le |
| Length | 1 byte | 1 byte | 1 byte | 1 byte | 1 byte | Lc byte | 1 byte |
| Class byte 0x00: standard command 0xA2: ST command | | | | | | | |
| Instruction byte | | | | | | | |
| Param Byte 1 | | | | | | | |
| Param Byte 2 | | | | | | | |
| Number of bytes of the Data field | | | | | | | |
| Data bytes | | | | | | | |
| Number of bytes to be read in the M24SR64-Y memory | | | | | | | |

5.2.2 R-APDU: payload format of a response

the M24SR64-Y uses the I-Block format to reply to a command which used the I-Block format. This format is described in [Table 17](#).

Table 17. R-APDU format

| Name | Payload field | | |
|---------------|-----------------|--------|--------|
| | Data (optional) | SW1 | SW2 |
| Length | Le byte | 1 byte | 1 byte |
| Data | | | |
| Status byte 1 | | | |
| Status byte 2 | | | |

5.3 R-Block format

The R-Block is used to convey positive or negative acknowledgment between the RF or I²C host and the M24SR64-Y.

Table 18. R-Block format

| PCB | CRC |
|--|-------------|
| R(ACK) without the DID field: 0xA2 or 0xA3 R(ACK) with the DID field: 0xAA or 0xAB R(NAK) without the DID field: 0xB2 0xB3 R(NAK) with the DID field: 0xBA 0xBB | 2 CRC bytes |

There are two kinds of R-Blocks:

- R(ACK): the acknowledgement block sent by the RF or I²C host or by the M24SR64-Y
- R(NAK): the non-acknowledgement block sent by the RF or I²C host or by the M24SR64-Y

Table 19. R-Block detailed format

| | b7-b6 | b5 | b4 | b3 | b2 | b1 | b0 |
|--|-------|----|----|----|----|----|----|
| | 0b10 | 1 | X | X | 0 | 0 | X |
| R-Block | | | | | | | |
| RFU | | | | | | | |
| 0: NAK 1: ACK | | | | | | | |
| 0: DID field is not present 1: DID field is present | | | | | | | |
| Must be set to 0 | | | | | | | |
| RFU | | | | | | | |
| Block number | | | | | | | |

5.4 S-Block format

The S-Block is used to exchange control information between a reader and a contactless tag.

Table 20. S-Block format

| NFC frame | SoD | | Payload | EoD |
|--|--------|--------|----------------|---------|
| | PCB | DID | | |
| Length | 1 byte | 1 byte | 1 to 255 bytes | 2 bytes |
| 0xC2: for S(DES) when the DID field is not present 0xCA: for S(DES) when the DID field is present 0xF2: for S(WTX) when the DID field is not present 0xFA: for S(WTX) when the DID field is present | | | | |
| DID field (optional) | | | | |
| WTX field ⁽¹⁾ | | | | |
| 2 CRC bytes | | | | |

1. This field is present when b5-b4 bits are set to 0b11 (S-Block is a WTX). see [Table 21: S-Block detailed format](#).

There are two requests using the S-Block format:

- S(DES): the deselect command
- S(WTX): the Waiting Frame eXtension command or response.

A Waiting Time eXtension request occurs, in RF or I²C, when the operating time needed by M24SRxx is greater than 9.6 ms.

The WTX field indicates the increase time factor to be used in this command execution (FDTtemp = WTX * 9.6 ms).

Table 21. S-Block detailed format

| | b7-b6 | b5-b4 | b3 | b2 | b1 | b0 |
|-----------------------------|-------|-------|----|----|----|----|
| | 0b11 | X | X | 0 | 1 | 0 |
| S-Block | | | | | | |
| 0b00: Deselect | | | | | | |
| 0b11: WTX | | | | | | |
| 0: DID field is not present | | | | | | |
| 1: DID field is present | | | | | | |
| - | | | | | | |
| RFU | | | | | | |
| RFU | | | | | | |

Note: After receiving the deselect command, the session is released and M24SR64-Y enters the Standby power mode.

In response to a RATS command, M24SR64-Y returns FWI parameter (default frame waiting time used); when M24SR64-Y needs more time for a command execution, it requests a frame waiting time extension by responding 0xF2 0xWTX (Request waiting time = FWI * WTX). If the reader accepts M24SR64-Y request, it acknowledges by sending the command 0xF2 0xWTX. The frame waiting time becomes FWI * WTX for the current command only.

5.5 CRC of the I²C and RF frame

The two CRC bytes check the data transmission between the RF host or I²C host and the M24SR64-Y. For the RF frame, the CRC is computed on all the data bits in the frame, excluding parity bits, SOF and EOF, and the CRC itself.

For the I²C frames, the CRC is computed on all data bits of the frame excluding Device select and the CRC itself.

The CRC is as defined in ISO/IEC 13239. The initial register content shall be 0x6363 and the register content shall not be inverted after calculation.

5.6 NFC Forum Type 4 Tag protocol

5.6.1 Commands set

With the NFC Forum Type 4 Tag protocol, the commands are common to RF and I²C.

Table 22. Command set overview

| Command name | Brief description |
|-----------------------------|--|
| NDEF Tag Application Select | Select the NDEF Tag Application |
| Capability Container Select | Select the capability container (CC) file using the Select command |

Table 22. Command set overview (continued)

| Command name | Brief description |
|--------------------|--------------------------|
| NDEF Select | Select the NDEF file |
| System File Select | Select the system file |
| ReadBinary | Read data from a file |
| UpdateBinary | Write new data to a file |

5.6.2 Status and error codes

This section lists the status and the error code of the M24SR64-Y.

Table 23. Status code of the M24SR64-Y

| | SW1 | SW2 | Comment |
|-------|------|------|--------------------------------|
| Value | 0x90 | 0x00 | Command completed successfully |

Table 24. Error code of the M24SR64-Y

| | SW1 | SW2 | Comment |
|---------------|---------------|---------------|--|
| Length | 1 byte | 1 byte | |
| Value | 0x62 | 0x80 | File overflow (Le error) |
| Value | 0x62 | 0x82 | End of file or record reached before reading Le bytes |
| Value | 0x63 | 0x00 | Password is required |
| Value | 0x63 | 0xCX | Password is incorrect, X further retries allowed (X can take value 0,1, 2) |
| Value | 0x65 | 0x81 | Unsuccessful updating |
| Value | 0x67 | 0x00 | Wrong length |
| Value | 0x69 | 0x81 | Cmd is incompatible with the file structure |
| Value | 0x69 | 0x82 | Security status not satisfied |
| Value | 0x69 | 0x84 | Reference data not usable |
| Value | 0x6A | 0x80 | Incorrect parameters Le or Lc |
| Value | 0x6A | 0x82 | File or application not found |
| Value | 0x6A | 0x84 | File overflow (Lc error) |
| Value | 0x6A | 0x86 | Incorrect P1 or P2 values |
| Value | 0x6D | 0x00 | INS field not supported |
| Value | 0x6E | 0x00 | Class not supported |

5.6.3 NDEF Tag Application Select command

the RF or the I²C host shall send this command to activate the NDEF Tag Application.

To activate the NDEF Tag Application, the RF host sends the Select command (see [Table 25](#)) in addition to the sequence defined in the NFC Forum digital protocol.

To activate the NDEF Tag Application, the I²C host sends the Select command (see [Table 25](#)) in addition to the GetSession or the Kill RF session command.

[Table 25](#) defines the C-APDU of the Select command to select the NDEF Tag Application (called NDEF Tag Application Select).

Table 25. C-APDU of the NDEF Tag Application Select command

| Name | CLA | INS | P1 | P2 | Lc | Data | Le |
|-------------------------|------|------|------|------|------|----------------------|------|
| Value | 0x00 | 0xA4 | 0x04 | 0x00 | 0x07 | 0xD27600 00850101 | 0x00 |
| Class byte | | | | | | | |
| Select instruction code | | | | | | | |
| P1 field | | | | | | | |
| P2 field | | | | | | | |
| Number of bytes of data | | | | | | | |
| Application ID | | | | | | | |
| Le field | | | | | | | |

[Table 26](#) defines the R-APDU of the NDEF Tag Application Select command.

Table 26. R-APDU of the NDEF Tag Application Select command

| | Data | SW1 | SW2 | Comment |
|--------|------|--------|--------|--------------------------------|
| Length | - | 1 byte | 1 byte | - |
| Value | - | 0x90 | 0x00 | Command completed |
| Value | - | 0x6A | 0x82 | NDEF Tag Application not found |
| Value | - | 0x6D | 0x00 | Class not supported |

5.6.4 Capability Container Select command

The RF or I²C host uses the Capability Container Select procedure to select the capability container (CC) file.

The CC file is selected when this command returns "command completed" in the R-APDU. [Table 27](#) defines the C-APDU of the Select command to select the CC file (called Capability Container Select).

Table 27. C-APDU of the Capability Container Select command

| Name | CLA | INS | P1 | P2 | Lc | Data | Le |
|-------------------------|------|------|------|------|------|--------|----|
| Value | 0x00 | 0xA4 | 0x00 | 0x0C | 0x02 | 0xE103 | - |
| Class byte | | | | | | | |
| Select instruction code | | | | | | | |
| P1 field | | | | | | | |
| P2 field | | | | | | | |
| Number of bytes of data | | | | | | | |
| CC file ID | | | | | | | |
| - | | | | | | | |

Table 28 defines the R-APDU of the CC Select command.

Table 28. R-APDU of the Capability Container Select command

| | Data | SW1 | SW2 | Comment |
|--------|------|--------|--------|-------------------------------|
| Length | - | 1 byte | 1 byte | - |
| Value | - | 0x90 | 0x00 | Command completed |
| Value | - | 0x6A | 0x82 | File or application not found |
| Value | - | 0x6D | 0x00 | Class not supported |

5.6.5 NDEF Select command

The RF or I²C host uses the NDEF Select command to select the NDEF file.

The NDEF file is selected when this command returns "command completed" in the R-APDU. *Table 29* defines the C-APDU of the Select command to select the NDEF file (called NDEF Select).

Table 29. C-APDU of the NDEF Select command

| Name | CLA | INS | P1 | P2 | Lc | Data | Le |
|-------------------------|------|------|------|------|------|--------|----|
| Value | 0x00 | 0xA4 | 0x00 | 0x0C | 0x02 | 0x000X | - |
| Class byte | | | | | | | |
| Select instruction code | | | | | | | |
| P1 field | | | | | | | |
| P2 field | | | | | | | |
| Number of bytes of data | | | | | | | |
| 0x0001: first NDEF file | | | | | | | |
| - | | | | | | | |

[Table 30](#) defines the R-APDU of the NDEF Select command.

Table 30. R-APDU of the NDEF Select command

| | Data | SW1 | SW2 | Comment |
|--------|------|--------|--------|-------------------------------|
| Length | - | 1 byte | 1 byte | - |
| Value | - | 0x90 | 0x00 | Command completed |
| Value | - | 0x6A | 0x82 | File or application not found |

5.6.6 System File Select command

The RF or I²C host uses this command to select the system file.

The System file is selected when this command returns "command completed" in the R-APDU.

[Table 31](#) defines the C-APDU of the command to select the System file (called System Select).

Table 31. C-APDU of the System File Select command

| Name | CLA | INS | P1 | P2 | Lc | Data | Le |
|-------------------------|------|------|------|------|------|--------|----|
| | 0x00 | 0xA4 | 0x00 | 0x0C | 0x02 | 0xE101 | - |
| Class byte | | | | | | | |
| Select instruction code | | | | | | | |
| P1 field | | | | | | | |
| P2 field | | | | | | | |
| Number of bytes of data | | | | | | | |
| System file ID | | | | | | | |
| - | | | | | | | |

[Table 32](#) defines the R-APDU of the System File Select command.

Table 32. R-APDU of the System File Select command

| | Data | SW1 | SW2 | Comment |
|--------|------|--------|--------|---|
| Length | - | 1 byte | 1 byte | - |
| Value | - | 0x90 | 0x00 | Command completed |
| Value | - | 0x6A | 0x82 | Capability container not found, no data is returned |

5.6.7 ReadBinary command

On receiving the ReadBinary command, the M24SR64-Y reads the requested memory field and sends back its value in the R-APDU response.

Before sending a ReadBinary command, a file shall be selected by using a Select command.

The Response of the ReadBinary command is successful when the data to be read is within the selected file ^(a); in other words, when the sum of P1-P2 and Le fields is equal to or lower than the selected file length.

[Table 33](#) defines the ReadBinary command.

Table 33. C-APDU of the ReadBinary command

| Name | CLA | INS | P1 & P2 | Lc | Data | Le |
|--|------|------|---------|----|------|--------|
| | 0x00 | 0xB0 | 2 bytes | - | - | 1 byte |
| Class byte | | | | | | |
| Read instruction code | | | | | | |
| Offset in the file selected | | | | | | |
| - | | | | | | |
| - | | | | | | |
| Number of bytes to read between 0x01 ≤Le ≤max(Selected File length, 0xF6) | | | | | | |

[Table 34](#) defines the R-APDU of the ReadBinary command.

Table 34. R-APDU of the ReadBinary command

| | Data | SW1 | SW2 | Comment |
|--------|--------------|--------|--------|-------------------------------|
| Length | - | 1 byte | 1 byte | - |
| Value | Content read | 0x90 | 0x00 | Command completed |
| Value | - | 0x67 | 0x00 | Wrong length |
| Value | - | 0x69 | 0x82 | Security status not satisfied |
| Value | - | 0x6A | 0x82 | File or application not found |
| Value | - | 0x6E | 0x00 | Class not supported |

5.6.8 UpdateBinary command

On receiving the UpdateBinary command, the M24SR64-Y writes the data field into the selected file and sends back a status in the R-APDU response. If needed, M24SR will request a timing extension (see [Section 5.4](#)).

Before sending an UpdateBinary command, a file shall be selected by issuing a Select command.

[Table 35](#) defines the UpdateBinary command.

- a. For more details about CC file, refer to [Section 3.1.2: CC file layout](#).
 For more details about NDEF file, refer to [Section 3.1.3: NDEF file layout](#).
 For more details about System file, refer to [Section 3.1.4: System file layout](#).

Table 35. C-APDU of the UpdateBinary command

| Name | CLA | INS | P1 & P2 | Lc | Data | Le |
|--|------|------|---------|--------|----------|----|
| | 0x00 | 0xD6 | 2 bytes | 1 byte | Lc bytes | - |
| Class byte | | | | | | |
| Write instruction code | | | | | | |
| Offset in the file selected | | | | | | |
| Number of bytes of data (0x01 ≤ Lc ≤ 0xF6) | | | | | | |
| Data to write in the M24SR64-Y memory | | | | | | |
| - | | | | | | |

[Table 36](#) defines the R-APDU of the UpdateBinary command.

Table 36. R-APDU of the UpdateBinary command

| | Data | SW1 | SW2 | Comment |
|--------|------|--------|--------|-------------------------------|
| Length | - | 1 byte | 1 byte | - |
| Value | - | 0x90 | 0x00 | Command completed |
| Value | - | 0x65 | 0x81 | Unsuccessful updating |
| Value | - | 0x67 | 0x00 | Wrong length |
| Value | - | 0x69 | 0x82 | Security status not satisfied |
| Value | - | 0x6A | 0x82 | File or application not found |
| Value | - | 0x6E | 0x00 | Class not supported |

Note: For further return codes and definitions, refer to [Status and error codes](#).

5.7 ISO/IEC 7816-4 commands

The ISO/IEC 7816-4 command set offers some extended features such as the protection of the NDEF file. This command set is used to manage the right access of the NDEF file.

5.7.1 Verify command

The Verify command has two functions:

1. Check if a password is required to access to the NDEF file (the LC field = 0x00).
2. Check that the password embedded in the Verify command allows the access to the memory (the Lc field = 0x10 and the password is present).

When the Lc field is equal to 0x00, the verify command returns a success code (0x90 00) provided that the access to the NDEF file does not require a password. When the access to the NDEF file is protected, the response to the Verify command returns an error code (0x63 00).

When the Lc field equals 0x10, on receiving the Verify command, the M24SR64-Y compares the requested password with the data contained in the request and reports whether the operation has been successful in the response.

Before sending this command, an NDEF file shall be selected by issuing the NDEF Select command. Thus, this command checks the right access condition of the last NDEF file selected.

After a successful command, an access is granted for the whole NDEF file.

[Table 37](#) defines the Verify command.

Table 37. Verify command format

| Name | CLA | INS | P1 & P2 | Lc | Data | Le |
|---|------|------|---------|--------|----------|----|
| | 0x00 | 0x20 | 2 bytes | 1 byte | Lc bytes | - |
| Class byte | | | | | | |
| Instruction code | | | | | | |
| Password identification | | | | | | |
| 0x0001: Read NDEF password transmit | | | | | | |
| 0x0002: Write NDEF password transmit | | | | | | |
| 0x0003: I ² C password transmit ⁽¹⁾ | | | | | | |
| Other: RFU | | | | | | |
| 0x00: the password is not present | | | | | | |
| 0x10: the password is present in the data field | | | | | | |
| Password | | | | | | |
| - | | | | | | |

1. This code can only be issued by the I²C host.

Table 38 defines the R-APDU of the Verify command.

Table 38. R-APDU of the Verify command

| | Data | SW1 | SW2 | Comment |
|--------|------|--------|---------------------|--|
| Length | - | 1 byte | 1 byte | - |
| Value | - | 0x90 | 0x00 | Command completed, the password is correct |
| Value | - | 0x69 | 0x85 | The conditions of use are not satisfied (e.g. no NDEF file was selected) |
| Value | - | 0x69 | 0x81 | Cmd incompatible with file structure |
| Value | - | 0x69 | 0x82 | Security status not satisfied |
| Value | - | 0x6A | 0x80 | Incorrect parameter in cmd data field |
| Value | - | 0x63 | 0x00 | A password is required |
| Value | - | 0x63 | 0xCX ⁽¹⁾ | The password transmitted is incorrect and X encodes the number of further allowed retries. |
| Value | - | 0x6E | 0x00 | Class not supported |

1. At each session, the RF or I²C host can check a password 3 times.

5.7.2 Change Reference Data command

The Change Reference Data command replaces the read or write password related to the NDEF files previously selected. It can be performed only if the security status satisfies the security attributes for this command.

Before sending this command, the verify command with the correct NDEF write password shall be issued. Thus, this command changes the reference data of the NDEF file.

Table 39 defines the Change Reference Data command.

Table 39. Change reference data command format

| Name | CLA | INS | P1 & P2 | Lc | Data | Le |
|---|------|------|---------|--------|----------|----|
| | 0x00 | 0x24 | 2 bytes | 1 byte | Lc bytes | - |
| Class byte | | | | | | |
| Instruction code | | | | | | |
| Password identification | | | | | | |
| 0x0001: Read password transmit | | | | | | |
| 0x0002: Write password transmit | | | | | | |
| 0x0003: I ² C password transmit ⁽¹⁾ | | | | | | |
| Other: RFU | | | | | | |
| 0x10: the password is present in the data field | | | | | | |
| NDEF file or I ² C Password | | | | | | |
| - | | | | | | |

1. This code can only be issued by the I²C host.

[Table 40](#) defines the R-APDU of the Change Reference Data command.

Table 40. R-APDU of the Change Reference Data command

| | Data | SW1 | SW2 | Comment |
|--------|------|--------|--------|--|
| Length | 0 | 1 byte | 1 byte | - |
| Value | - | 0x90 | 0x00 | Command completed, the access right has been changed |
| Value | - | 0x69 | 0x81 | Cmd is incompatible with the file structure |
| Value | - | 0x65 | 0x81 | Unsuccessful updating |
| Value | - | 0x69 | 0x82 | Security status not satisfied |
| Value | - | 0x6A | 0x80 | CC file or System file selected |
| Value | - | 0x6A | 0x82 | File or application not found |
| Value | - | 0x6A | 0x86 | Incorrect P1 or P2 values |
| Value | - | 0x6E | 0x00 | Class not supported |

5.7.3 Enable Verification Requirement command

The Enable Verification Requirement command activates the protection by password of the NDEF file. When this command is successful, the read or write access to the NDEF file is protected by a 128-bit password. It can be performed only if the security status satisfies the security attributes for this command.

This command can update the right access of the NDEF file by writing into the EEPROM. In this case, the response timing will be around 5 ms.

Before sending this command, the verify command with the correct NDEF write password shall be issued. Thus, this command changes the access right of the NDEF file.

[Table 41](#) defines the Enable Verification requirement command.

Table 41. Enable Verification Requirement command format

| Name | CLA | INS | P1 & P2 | Lc | Data | Le |
|--|------|------|---------|----|------|----|
| | 0x00 | 0x28 | 2 bytes | - | - | - |
| Class byte | | | | | | |
| Instruction code | | | | | | |
| New security attributes | | | | | | |
| 0x0001: Enable the read protection of the NDEF file | | | | | | |
| 0x0002: Enable the write protection of the NDEF file | | | | | | |
| Other: RFU | | | | | | |
| - | | | | | | |
| - | | | | | | |
| - | | | | | | |

The last five bits identify the password sent in the Verify command.

[Table 42](#) defines the R-APDU of the Enable Verification Requirement command.

Table 42. R-APDU of the Enable Verification Requirement command

| | Data | SW1 | SW2 | Comment |
|--------|------|--------|--------|---|
| Length | 0 | 1 byte | 1 byte | - |
| Value | - | 0x90 | 0x00 | Command completed, the password is correct |
| Value | - | 0x69 | 0x81 | Cmd is incompatible with the file structure |
| Value | - | 0x69 | 0x82 | Security status not satisfied |
| Value | - | 0x6A | 0x80 | CC file or System file selected |
| Value | - | 0x6A | 0x82 | File or application not found |
| Value | - | 0x6A | 0x86 | Incorrect P1 or P2 values |

5.7.4 Disable Verification Requirement command

The Disable Requirement command deactivates the protection by password of the NDEF file. When this command is successful, the read or write access to the NDEF file is granted without security requirements. It can be performed only if the security status satisfies the security attributes for this command.

Before sending this command, the verify command with the correct NDEF write password shall be issued. Thus, this command changes the access right of the NDEF file.

This command can update the right access of the NDEF file by writing into the EEPROM. In this case, the response timing will be around 6 ms.

[Table 43](#) defines the Disable Verification Requirement command.

Table 43. Disable Verification Requirement command format

| Name | CLA | INS | P1 & P2 | Lc | Data | Le |
|---|------|------|---------|----|------|----|
| | 0x00 | 0x26 | 2 bytes | - | - | - |
| Class byte | | | | | | |
| Instruction code | | | | | | |
| New security attributes | | | | | | |
| 0x0001: Disable the read protection of the NDEF file | | | | | | |
| 0x0002: Disable the write protection of the NDEF file | | | | | | |
| Other: RFU | | | | | | |
| - | | | | | | |
| - | | | | | | |
| - | | | | | | |

[Table 44](#) defines the R-APDU of the Disable Verification Requirement command.

Table 44. R-APDU of the Disable Verification Requirement command

| | Data | SW1 | SW2 | Comment |
|--------|------|--------|--------|---|
| Length | 0 | 1 byte | 1 byte | - |
| Value | - | 0x90 | 0x00 | Command completed, the password is correct |
| Value | - | 0x69 | 0x81 | Cmd is incompatible with the file structure |
| Value | - | 0x69 | 0x82 | Security status not satisfied |
| Value | - | 0x6A | 0x80 | CC file or System file selected |
| Value | - | 0x6A | 0x82 | File or application not found |
| Value | - | 0x6A | 0x86 | Incorrect P1 or P2 values |
| Value | - | 0x6E | 0x00 | Class not supported |
| Value | - | 0x65 | 0x81 | Update failed |

5.8 ST Proprietary command set

The RF or I²C host can be issued with the command set described in this chapter.

5.8.1 ExtendedReadBinary command

On receiving the ExtendedReadBinary command, the M24SR64-Y reads the requested memory field and sends back its value in the R-APDU response.

Before sending an ExtendedReadBinary command, a file shall be selected by issuing an NDEF select command.

The response of the ExtendedReadBinary command will be successful even if the data to be read is beyond the NDEF message. The command returns an error code if the data to be read is outside the memory plan.

Table 45. C-APDU of the ExtendedReadBinary command

| Name | CLA | INS | P1 & P2 | Lc | Data | Le |
|--|------|------|---------|----|------|--------|
| Length | 0xA2 | 0xB0 | 2 bytes | - | - | 1 byte |
| ST Class byte | | | | | | |
| Read instruction code | | | | | | |
| Offset in the file selected | | | | | | |
| - | | | | | | |
| - | | | | | | |
| - | | | | | | |
| Number of bytes to read between 0x01 ≤ Le ≤ 0xF6 | | | | | | |

[Table 46](#) defines the R-APDU of the read binary command.

Table 46. R-APDU of the ExtendedReadBinary command

| | Data | SW1 | SW2 | comment |
|--------|--------------|--------|--------|-------------------------------|
| Length | Le bytes | 1 byte | 1 byte | - |
| Value | Content read | 0x90 | 0x00 | Command completed |
| Value | - | 0x67 | 0x00 | Wrong length |
| Value | - | 0x69 | 0x82 | Security status not satisfied |
| Value | - | 0x6A | 0x82 | File or application not found |
| Value | - | 0x6A | 0x86 | Incorrect P1 or P2 values |
| Value | - | 0x6E | 0x00 | Class not supported |

5.8.2 EnablePermanentState command

The command configures the NDEF file to the ReadOnly or to the WriteOnly State.

This command can update the right access to the NDEF file by writing into the EEPROM. In this case, the response timing will be around 6 ms.

[Table 47](#) defines the EnablePermanentState requirement command.

Table 47. EnablePermanentState command format

| Name | CLA | INS | P1 & P2 | Lc | Data | Le |
|--|------|------|---------|----|------|----|
| Length | 0xA2 | 0x28 | 2 bytes | - | - | - |
| Class byte | | | | | | |
| Instruction code | | | | | | |
| New security attributes | | | | | | |
| 0x0001: Enable the read protection of the NDEF file | | | | | | |
| 0x0002: Enable the write protection of the NDEF file | | | | | | |
| Other: RFU | | | | | | |
| - | | | | | | |
| - | | | | | | |
| - | | | | | | |
| - | | | | | | |

[Table 48](#) defines the R-APDU of the EnablePermanentState command.

Table 48. R-APDU table of the EnablePermanentState command

| | Data | SW1 | SW2 | comment |
|--------|------|--------|--------|-------------------|
| Length | - | 1 byte | 1 byte | - |
| Value | - | 0x90 | 0x00 | Command completed |
| Value | - | 0x65 | 0x81 | Update failed |
| Value | - | 0x67 | 0x00 | Wrong length |

Table 48. R-APDU table of the EnablePermanentState command (continued)

| | Data | SW1 | SW2 | comment |
|-------|------|------|------|---------------------------------|
| Value | - | 0x69 | 0x82 | Security status not satisfied |
| Value | - | 0x6A | 0x80 | CC file or System file selected |
| Value | - | 0x6A | 0x82 | File or application not found |
| Value | - | 0x6A | 0x86 | Incorrect P1 or P2 values |
| Value | - | 0x6E | 0x00 | Class not supported |

5.8.3 DisablePermanentState command

The command configures the NDEF file to the Lock state.

This command can update the right access of the NDEF file by writing into the EEPROM. In this case, the response timing will be around 6 ms. This command is only valid in I²C. The SuperUser rights must have been granted to execute the command.

Before sending this command, an NDEF file shall be selected by issuing the NDEF Select command.

[Table 49](#) defines the DisablePermanentState requirement command.

Table 49. DisablePermanentState command format

| Name | CLA | INS | P1 & P2 | Lc | Data | Le |
|---|------|------|---------|----|------|----|
| Length | 0xA2 | 0x26 | 2 bytes | - | - | - |
| Class byte | | | | | | |
| Instruction code | | | | | | |
| New security attributes | | | | | | |
| 0x0001: Disable the read protection of the NDEF file | | | | | | |
| 0x0002: Disable the write protection of the NDEF file | | | | | | |
| Other: RFU | | | | | | |
| - | | | | | | |
| - | | | | | | |
| - | | | | | | |

[Table 50](#) defines the R-APDU of the DisablePermanentState command.

Table 50. R-APDU of the DisablePermanentState command

| | Data | SW1 | SW2 | comment |
|--------|------|--------|--------|-------------------------------|
| Length | - | 1 byte | 1 byte | - |
| Value | - | 0x90 | 0x00 | Command completed |
| Value | - | 0x65 | 0x81 | Update failed |
| Value | - | 0x67 | 0x00 | Wrong length |
| Value | - | 0x69 | 0x82 | Security status not satisfied |

Table 50. R-APDU of the DisablePermanentState command (continued)

| | Data | SW1 | SW2 | comment |
|-------|------|------|------|---------------------------------|
| Value | - | 0x6A | 0x80 | CC file or System file selected |
| Value | - | 0x6A | 0x82 | File or application not found |
| Value | - | 0x6A | 0x86 | Incorrect P1 or P2 values |
| Value | - | 0x6E | 0x00 | Class not supported |

5.8.4 SendInterrupt command

On receiving the SendInterrupt command, the M24SR64-Y generates a negative pulse on the GPO pin. It starts at the end of the command and ends at the end of the RF response.

Before sending this command, the system file shall be selected by issuing the System Select command.

[Table 51](#) defines the SendInterrupt command.

Table 51. SendInterrupt command format

| | CLA | INS | P1&P2 | Lc | Data | Le |
|--------|--------|--------|---------|--------|------|----|
| Length | 1 byte | 1 byte | 2 bytes | 1 byte | - | - |
| Value | 0xA2 | 0xD6 | 0x001E | 0x00 | - | - |

[Table 52](#) describes the R-APDU of the SendInterrupt command.

Table 52. R-APDU of the SendInterrupt command

| | Data | SW1 | SW2 | Comment |
|--------|------|--------|--------|--|
| Length | - | 1 byte | 1 byte | - |
| Value | - | 0x90 | 0x00 | The interrupt has been sent |
| Value | - | 0x6A | 0x80 | The GPO is not configured as an interrupt mode |
| Value | - | 0x6A | 0x82 | File or application not found |
| Value | - | 0x6A | 0x86 | Incorrect P1 or P2 values |
| Value | - | 0x6E | 0x00 | Class not supported |

5.8.5 StateControl command

On receiving the StateControl command with reset value: data 0x00, the M24SR64-Y drives the GPO pin low. On receiving the StateControl command with set value: data 0x01, the M24SR64-Y releases the GPO pin which returns to HZ.

Before sending this command, the system file shall be selected by issuing the System Select command.

[Table 53](#) defines the State Control command.

Table 53. StateControl command format

| | CLA | INS | P1&P2 | Lc | Data | Le |
|-------------|--------|--------|---------|--------|------|----|
| Length | 1 byte | 1 byte | 2 bytes | 1 byte | - | - |
| Reset value | 0xA2 | 0xD6 | 0x001F | 0x01 | 0x00 | - |
| Set value | 0xA2 | 0xD6 | 0x001F | 0x01 | 0x01 | - |

Table 54. R-APDU of the StateControl command

| | Data | SW1 | SW2 | Comment |
|--------|------|--------|--------|--|
| Length | - | 1 byte | 1 byte | - |
| Value | - | 0x90 | 0x00 | The set or reset has been sent |
| Value | - | 0x6A | 0x80 | The GPO is not configured in StateControl mode |
| Value | - | 0x6A | 0x82 | File or application not found |
| Value | - | 0x6A | 0x86 | Incorrect P1 or P2 values |
| Value | - | 0x6E | 0x00 | Class not supported |

5.9 Specific RF command set

This section describes the command set that can be issued only by the RF host.

5.9.1 Anticollision command set

[Table 55](#) lists the commands that can be issued only by the RF host. The format of these commands is described in the NFC Forum Digital Protocol specification.

Table 55. Commands issues by the RF host

| Family command set | Command name | Instruction code |
|--------------------|--------------|----------------------|
| NFC-A technology | ALL_REQ | 0x52 ⁽¹⁾ |
| | SENS_REQ | 0x26 ⁽¹⁾ |
| | SDD_REQ | 0x93 or 0x95 or 0x97 |
| | SEL_REQ | 0x93 or 0x95 or 0x97 |
| | SLP_REQ | 0x50 |

1. Code on 7 bits.

5.9.2 RATS command and ATS response

RATS command and ATS response are used for NFC Forum Type 4A Tag Platform Device Activation (as defined in NFC Forum Digital Protocol specification).

[Table 56](#) details the RATS command. This command shall be sent after the anticollision process.

Table 56. RATS command

| Name | INS | Param | | CRC |
|------------------|------|--------|-------|---------|
| Byte field | 0xE0 | 1 byte | | 2 bytes |
| Bit field | | b7-b4 | b3-b0 | |
| Instruction code | | | | |
| FSDI | | | | |
| DID (0 ≤DID ≤14) | | | | |
| 2 CRC bytes | | | | |

The FSDI field codes the FSD that defines the maximum size that an RF or I²C host is able to receive. [Table 57](#) gives the conversion from FSDI to FSD.

Table 57. Conversion from FSDI to FSD

| FSDI | 0x0 | 0x1 | 0x2 | 0x3 | 0x4 | 0x5 | 0x6 | 0x7 | 0x8 | 0x9h-0xE | 0xF |
|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|----------|-----|
| FSD | 16 | 24 | 32 | 40 | 48 | 64 | 96 | 128 | 256 | RFU | 256 |

The DID field defines the value of the addressed M24SR64-Y.

Table 58. ATS response

| Name | TL | T0 | TA(1) | TB(1) | | TC(1) | CRC |
|--|------|------|--------|--------|-------|-------|---------|
| Byte field | 0x05 | 0x78 | 1 byte | 1 byte | | 0x02 | 2 bytes |
| Bit field | | | | b8-b5 | b4-b1 | | |
| Length of the ATS response | | | | | | | |
| FSCI = 256 bytes | | | | | | | |
| The maximum ascending data rate is 106 kbps | | | | | | | |
| The maximum descending data rate is 106 kbps | | | | | | | |
| FWI field (9.6 ms when TB = 0x50) | | | | | | | |
| SFGI field (302 μs when TB = 0x50) | | | | | | | |
| The DID is supported | | | | | | | |
| 2 CRC bytes | | | | | | | |

The FSCI codes the FSC which stands for the maximum frame size that the M24SR64-Y is able to receive. The M24SR64-Y is able to receive up to 256 bytes of command. If the RF or I²C host sends a command with more than 256 bytes, the M24SR64-Y will not be able to treat the command and will not reply.

The FWI which stands for the Frame Waiting time Integer codes the FWT. This time corresponds to the maximum duration while an RF or I²C host shall send before sending the next command.

The SFGI which stands for the Start-up Frame Guard Time is the minimum time that the reader shall wait after receiving the response of the M24SR64-Y.

5.9.3 PPS command & response

PPS (Protocol and Parameter Selection) command and response are defined in ISO/IEC 14443-4, in the Protocol Activation of PICC Type A.

The PPS command allows to change the data rates of the ascending (RF host to M24SR64-Y) and descending (M24SR64-Y to RF host) data rates.

Table 59. PPS command

| - | Name | INS | | PPS0 | PPS1 | | | CRC |
|------|----------------------|-------|-------|------|--------|-------|-------|---------|
| | Byte field | 0xDX | | 0x11 | 1 byte | | | 2 bytes |
| | Bit field | b7-b4 | b3-b0 | | 0b0000 | b3-b2 | b1-b0 | |
| INS | Instruction code | | | | | | | |
| | DID | | | | | | | |
| | PPS1 is present | | | | | | | |
| PPS1 | RFU | | | | | | | |
| | Descending data rate | | | | | | | |
| | Ascending data rate | | | | | | | |
| | 2 CRC bytes | | | | | | | |

The ascending and descending data rates shall be coded as described in [Table 60](#).

Table 60. Ascending and descending data rate coding

| Value | 0b00 | 0b01 | 0b10 | 0b11 |
|-----------|----------|------|------|------|
| Data rate | 106 kbps | RFU | RFU | RFU |

When the M24SR64-Y is able to change both data rates, it returns the following response. The data rate of this response is 106 kbps; then, the M24SR64-Y changes the ascending and descending data rates.

[Table 61](#) gives the details of the PPS response.

Table 61. PPS response

| Name | INS | - | PPS0 |
|---------------|-------|-------|------|
| Byte field | 0xDX | - | 0x11 |
| Bit field | b8-b5 | b4-b1 | |
| Response code | | | |
| DID field | | | |
| 2 CRC bytes | | | |

5.10 Specific I²C command set

[Table 62](#) lists the commands that can only be issued by the I²C host.

Table 62. Specific I²C commands

| Command name | Format | Class byte | Instruction code | Brief description |
|---------------|--------|------------|------------------|---|
| GetI2Csession | - | - | 0x26 | Open an I ² C session when the RF session is not ongoing |
| KillRFsession | - | - | 0x52 | Kill the RF session and open an I ² C session |

5.10.1 GetI2Csession command

The GetI2Csession command opens an I²C session if an RF session is not ongoing.

[Table 63](#) defines the GetI2Csession command.

Table 63. GetI2Csession command format

| | INS |
|--------|--------|
| Length | 1 byte |
| Value | 0x26 |

The GetI2Csession command does not create a reply.

When an RF session is ongoing, the M24SRxx will not acknowledge the command.

When no RF session is ongoing, the M24SRxx will acknowledge the command and open an I²C session.

5.10.2 KillRFsession command

The KillRFsession command closes the RF session and opens an I²C session.

[Table 64](#) defines the KillRFsession command.

Table 64. KillRFsession command format

| | INS |
|--------|--------|
| Length | 1 byte |
| Value | 0x52 |

The KillRFsession command does not create a reply. The RF session is closed when the device acknowledges the command.

Caution: A successful completion of the RF command is not certain.

6 RF device operation

6.1 Anticollision and Device Activation command set for the RF interface

The M24SR64-Y device supports the command set defined in the NFC-A Technology and the Type 4A Tag Platform chapters of the NFC Digital Protocol V1.0 specification.

6.2 Open an RFsession

Once the RF host has terminated the anticollision procedure and retrieve the ATS response, it shall send the SelectApplication command. The M24SR64-Y will open an RF session. At this point, the RF host can send the applicative command set and the I²C cannot communicate with the M24SR64-Y without closing first the RF session using the I²C KillRFsession command.

6.3 Close an RFsession

The RF host can close the RF session by issuing one of these methods:

- send an S(DES) command
- turn off the RF field

6.4 Applicative command set

The applicative command set is composed of the following command sets:

- the NFC Forum Type 4 Tag command set
- the ISO/IEC 7816-4 command set
- the proprietary command set

7 I²C device operation

The M24SR64-Y device supports the I²C protocol. The device that controls the data transfer is known as the bus master, and the other one as the slave device. A data transfer can only be initiated by the bus master, which also provides the serial clock for synchronization. The M24SR64-Y device is a slave in all communications.

7.1 I²C communication protocol

The I²C communication is built on a system of command and reply exchange. The I²C host starts the communication by sending a request. Once a valid request is received by the M24SR64-Y device, it carries out an internal operation and creates its answer.

As defined in this document, and except for the GetI2C session and Kill RF session commands, the definition of a valid request is a command with a right CRC value.

Figure 12 shows an exchange of a command and a response between the I²C host and the M24SR64-Y. Once the I²C session is open, the I²C host can send a command. The command is composed of:

- a Device Select field with the R/W bit set to 0.
- the command field.

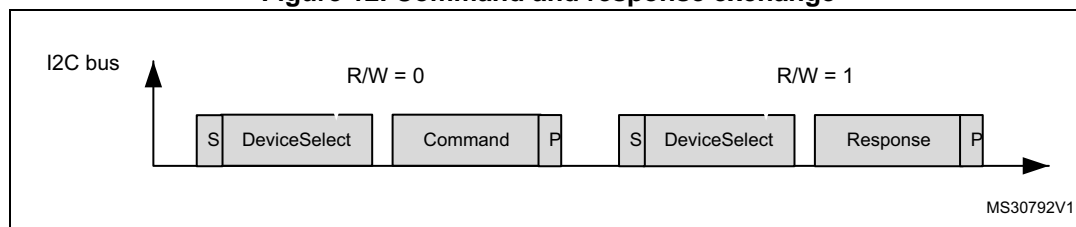
The M24SR64-Y acknowledges on the reception of each byte.

Once the M24SR64-Y is ready to send the answer, the I²C host shall:

- send a Device Select field with the R/W bit set to 1.
- release the SDA line and send an SCL clock.

The I²C host shall acknowledge on the reception of each byte.

Figure 12. Command and response exchange



Legend:

- S is the I²C Start bit sequence
- P is the I²C Stop bit sequence
- R/W is the 8th bit of Device Select.

Note: A restart during a command and response exchange is not supported by the M24SR64-Y. After a command, the I²C host can execute a Polling sequence to determine when the response is available.

Polling sequence: Loop on < START (S) + DeviceSelect with RW=0 + read NACK/ACK + STOP (P) >

The response is available as soon as the M24SR64-Y sends an ACK (host read will a '0').

7.2 Start condition

A Start condition is identified by a falling edge of serial data (SDA) while the serial clock (SCL) is stable in the high state. A Start condition must precede any data transfer command. The device continuously monitors (except during an instruction processing) the SDA and the SCL for a Start condition, and does not respond unless one is given.

7.3 Stop condition

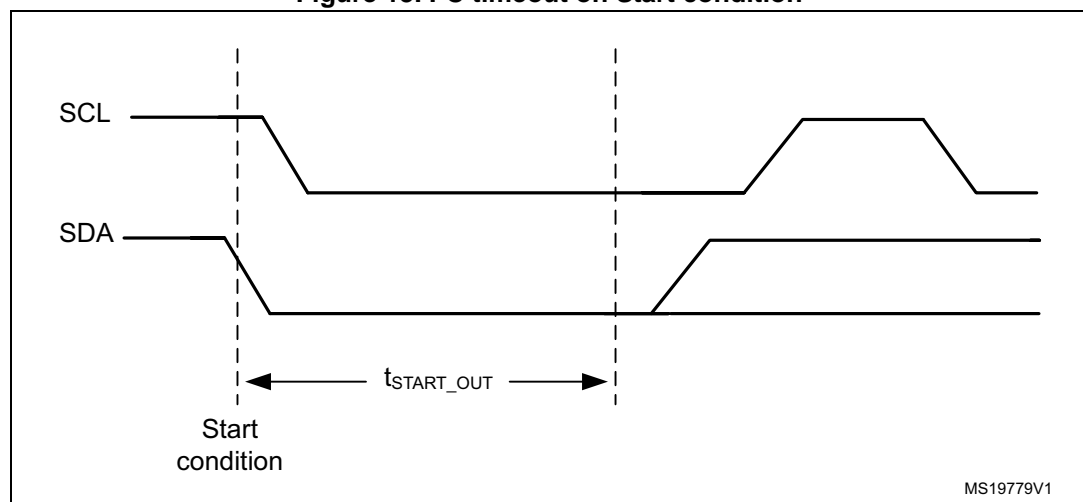
A Stop condition is identified by a rising edge of serial data (SDA) while the serial clock (SCL) is stable and driven high. A Stop condition terminates a command between the device and the bus master.

7.4 I²C timeout on Start condition

I²C communication with the M24SR64-Y starts with a valid Start condition, followed by a device select code.

If the delay between the Start condition and the following rising edge of the Serial Clock (SCL) that samples the most significant of the Device Select exceeds the $t_{\text{START_OUT}}$ time, the I²C logic block is reset and further incoming data transfer is ignored until the next valid Start condition.

Figure 13. I²C timeout on Start condition



7.5 I²C timeout on clock period

During a data transfer on the I²C bus, the serial clock high pulse width High (t_{CHCL}) or serial clock pulse width Low (t_{CLCH}) exceeds the maximum value specified in [Table 76](#), the I²C logic block is reset and any further incoming data transfer is ignored until the next valid Start condition.

7.6 Acknowledge bit (ACK)

The acknowledge bit is used to indicate a successful byte transfer. The bus transmitter, whether a bus master or a slave device, releases the serial data (SDA) after sending eight bits of data. During the 9th clock pulse period, the receiver pulls the SDA low to acknowledge the receipt of the eight data bits.

7.7 Data input

During data input, the device samples serial data (SDA) on the rising edge of the serial clock (SCL). For a correct device operation, the SDA must be stable during the rising edge of the SCL, and the SDA signal must change only when the SCL is driven low.

7.8 I²C device address

The device address is the concatenation of the group number coded on 4 bits and the I²C address coded on 3 bits, as shown in [Table 65](#).

Table 65. I²C device address format

| | b7-b4 | b3 | b2 | b1 | b0 |
|--------------|--------|----|----|----|-----|
| | 0b1010 | 1 | 1 | 0 | 0bx |
| Group number | | | | | |
| E2 bit | | | | | |
| E1 bit | | | | | |
| E0 bit | | | | | |
| 0 = Request | | | | | |
| 1 = Answer | | | | | |

7.9 I²C frame format

The I²C frame is composed of three fields:

1. SOD field: contains the device select and the PCB. The PCB field is detailed in [Section 5.2](#).
2. Payload field: contains the command and its parameter, as defined in the I²C command set.
3. EOD field: contains the two CRC bytes computed on the SOD but excluding the device select byte and the payload field.

[Table 66](#) shows the format of an I²C frame.

Table 66. I²C frame format

| I ² C frame | SOD | | Payload | EOD |
|--|--------------|--------|----------------|---------|
| | 0xAC or 0xAD | 1 byte | 1 to 251 bytes | 2 bytes |
| Device select 0xAC: to send a request to the M24SR64-Y 0xAD: to read a response of the M24SR64-Y | | | | |
| PCB field | | | | |
| I ² C command or I ² C answer | | | | |
| 2 CRC bytes | | | | |

7.9.1 Example of I²C frame commands

NDEF Tag Application command

This example presents the I²C frame of an NDEF Tag Application Select command. The I²C frame is detailed in [Table 67](#).

Table 67. I²C host to M24SR64-Y

| Field | SOD | | Payload | EOD |
|---------------------------------------|------|--------------|---------------|----------------|
| Value | 0xAC | 0x02 or 0x03 | Command field | 35 C0 or DF BE |
| Device select | | | | |
| PCB field | | | | |
| 0x00 A4 00 07 02 D2 76 00 00 85 01 01 | | | | |
| 2 CRC bytes | | | | |

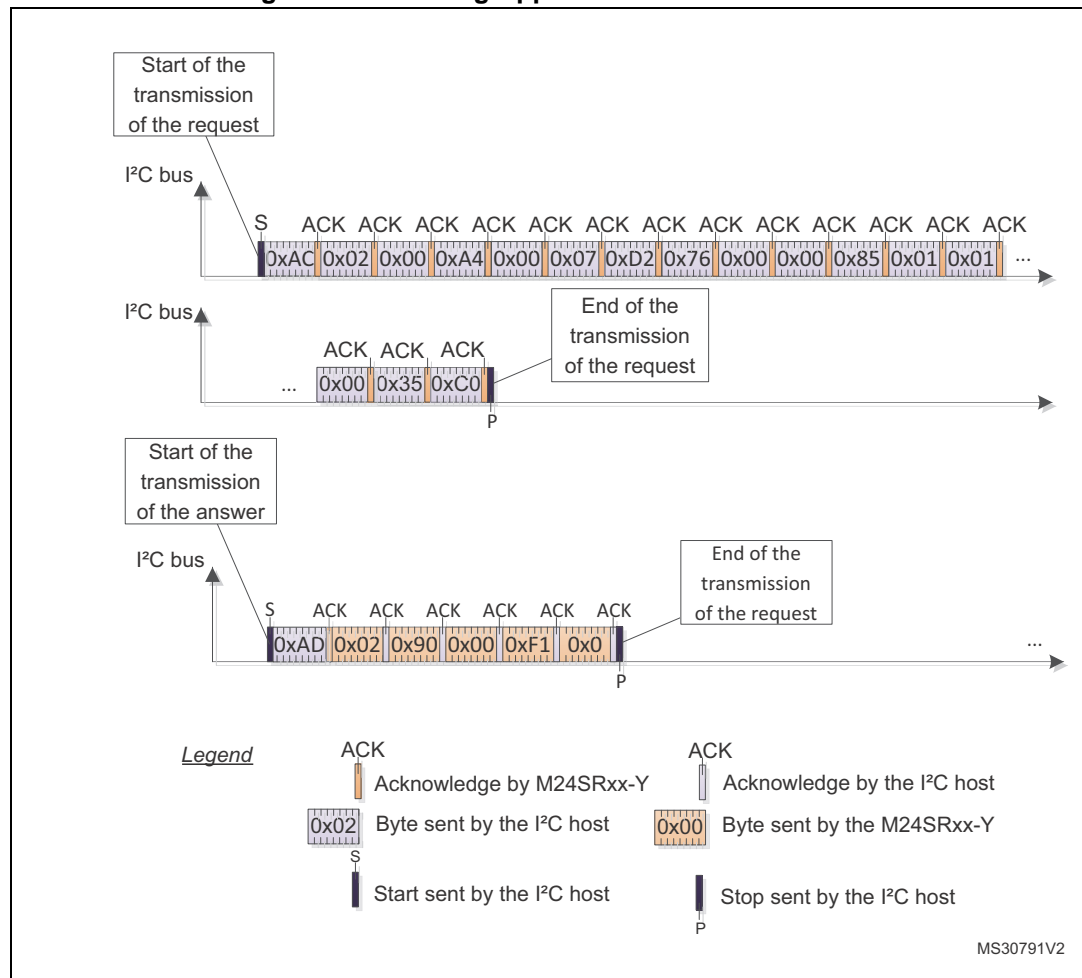
Before sending a new command, the I²C host can send an I²C frame to read the M24SR64-Y answer to the NDEF tag Application Select command.

Table 68. M24SR64-Y to I²C host

| Field | SOD | | Payload | EOD |
|--------------------------|------------------------------------|------------------------------------|---------|----------------|
| | I ² C host to M24SR64-Y | M24SR64-Y to I ² C host | | |
| Value | 0xAD | 0x02 or 0x03 | 0x90 00 | F1 09 or 2D 53 |
| Device select | | | | |
| PCB field | | | | |
| I ² C command | | | | |
| 2 CRC bytes | | | | |

[Figure 14](#) shows the I²C frame of the NDEF tag Application Select command.

Figure 14. NDEF tag Application Select command



7.10 Open an I2C session

To open an I2C session, the I2C host shall send either the GetSession command or the KillRFsession command. The GetSession Command opens an I2C session if an RF session is not currently opened.

A KillRFsession command closes the current RF session if it exists and opens an I2C session.

When an I2C session is opened, the RF host cannot communicate with the M24SR64-Y and cannot close the I2C session.

7.11 Close the I²C session

There are three ways to close an I²C session:

- turn off the Vcc power supply
- sent the S(DES) command
- wait for the I²C watchdog when it is enabled
- wait for the I²C timeout.

8 Functional procedures

This section describes some procedure to access the memory or manage its protection.

8.1 Selection of an NDEF message

The RF or I²C host shall use this procedure to detect the NDEF message inside an M24SR64-Y.

The NDEF detection procedure is as follows:

1. Open an RF or an I²C session
2. Send the SelectNDEFTagApplication command
3. Select the CC file
4. Read the CC file
5. Select the NDEF file.

8.2 Reading of an NDEF message

The RF or I²C host executes the NDEF read procedure to read the NDEF file.

1. Detect successfully the NDEF file using the NDEF detection procedure
2. Check that the read access without any security is granted for the NDEF file from the information provided by the CC file
3. Select the NDEF file
4. Read the NDEF file.

8.3 Reading a locked NDEF file

The RF or I²C host executes this procedure to read an NDEF file which has been locked previously.

1. Select the NDEF Tag Application
2. Select the NDEF file
3. Verify the Read password by using the Verify command
4. Read the data in the NDEF file.

8.4 Locking an NDEF file

The RF or I²C host executes this procedure to protect an NDEF file.

1. Select the NDEF Tag Application
2. Check the right access provided by the CC file
3. Select the NDEF file
4. Transmit the NDEF file Write password by using the Verify command
5. Lock the NDEF file by sending the Enable verification command.

8.5 Unlocking an NDEF file

The RF or I²C host executes this procedure to read an NDEF file which has been locked previously.

1. Select the NDEF Tag Application
2. Select the NDEF file
3. Verify the NDEF file Write password or the I²C password by using the Verify command
4. Unlock the NDEF file by sending the Disable verification command.

8.6 Reaching the read-only state for an NDEF file

The RF or I²C host executes this procedure to read an NDEF file which has been locked previously.

1. Select the NDEF Tag Application
2. Select the NDEF file
3. Transmit the NDEF file Write password or the I²C password by using the Verify command
4. Send an EnablePermanentState command as the Write access right of the previous Select NDEF file.

8.7 Changing an NDEF password procedure

The RF or I²C host could use this procedure to change one NDEF password. it can be a Read or Write password.

1. Select the NDEF Tag Application
2. Select the NDEF file
3. Transmit the NDEF file Write password or the I²C password by using the Verify command
4. Change the password by sending a ChangeReferenceData command.

9 UID: Unique identifier

The M24SR64-Y is uniquely identified by a 7 bytes unique identifier (UID). The UID is a read-only code and comprises:

- The IC manufacturer code on 1 byte (0x02 for STMicroelectronics).
- The Product code on 1 byte.
- A device number on 5 bytes.

Table 69 describes the UID format.

Table 69. UID format

| | 0x02 | 0x84 | 5 bytes |
|------------------------|------|------|---------|
| IC manufacturer code | | | |
| M24SR64-Y product code | | | |
| Device number | | | |

10 Maximum rating

Stressing the device above the rating listed in [Table 70](#) may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in the operating sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect the device reliability.

Table 70. Absolute maximum ratings

| Symbol | Parameter | | Min. | Max. | Unit |
|-----------------------------------|---|--|-------------------------|------------------|--------|
| T_A | Ambient operating temperature | | -40 | 85 | °C |
| T_{STG} , h_{STG} , t_{STG} | Storage conditions | Sawn wafer on UV tape | 15 | 25 | °C |
| | | | | 6 ⁽¹⁾ | months |
| | | kept in its original packing form | | | |
| T_{STG} | Storage temperature | UFDFPN8, SO8, TSSOP8 | -65 | 150 | °C |
| T_{STG} | Storage temperature | Sawn Bumped Wafer (kept in its antistatic bag) | 15 | 25 | °C |
| | Storage time | | | 6 | months |
| T_{LEAD} | Lead temperature during soldering | UFDFPN8, SO8, TSSOP8 | see note ⁽²⁾ | | °C |
| V_{IO} | I ² C input or output range | | -0.50 | 6.5 | V |
| I_{CC} ⁽³⁾ | RF supply current AC0 - AC1 | | - | 100 | mA |
| V_{MAX_1} ⁽³⁾ | RF input voltage amplitude between AC0 and AC1, GND pad left floating | VAC0-VAC1 | - | 10 | V |
| V_{MAX_2} ⁽³⁾ | AC voltage between AC0 and GND, or AC1 and GND | VAC0-GND or VAC1-GND | -0.5 | 4.5 | V |
| V_{ESD} | Electrostatic discharge voltage (human body model) ⁽⁴⁾ | AC0-AC1 | - | 1000 | V |
| V_{ESD} | Electrostatic discharge voltage (human body model) ⁽⁴⁾ | Other pads | - | 3500 | V |
| V_{ESD} | Electrostatic discharge voltage (Machine model) | | - | 150 | V |

1. Counted from ST shipment date.

2. Compliant with JEDEC Std J-STD-020D (for small body, Sn-Pb or Pb assembly), the ST ECOPACK[®] 7191395 specification, and the European directive on Restrictions on Hazardous Substances (ROHS directive 2011/65/EU, July 2011).

3. Based on characterization, not tested in production. Maximum absorbed power = 100 mW @ 7.5 A/m

4. AEC-Q100-002 (compliant with JEDEC Std JESD22-A114A, C1 = 100 pF, R1 = 1500 Ω, R2 = 500 Ω)

11 I²C DC and AC parameters

This section summarizes the operating and measurement conditions, and the DC and AC characteristics of the device in I²C mode. The parameters in the DC and AC characteristic tables that follow are derived from tests performed under the measurement conditions summarized in the relevant tables. Designers should check that the operating conditions in their circuit match the measurement conditions when relying on the quoted parameters.

Table 71. I²C operating conditions

| Symbol | Parameter | Min. | Max. | Unit |
|----------|-------------------------------|------|------|------|
| V_{CC} | Supply voltage | 2.7 | 5.5 | V |
| T_A | Ambient operating temperature | -40 | 85 | °C |

Table 72. AC test measurement conditions

| Symbol | Parameter | Min. | Max. | Unit |
|--------------|--|------------------------------|------|------|
| C_L | Load capacitance | 100 | | pF |
| t_r, t_f | Input rise and fall times | - | 50 | ns |
| V_{hi-lo} | Input levels | 0.2 V_{CC} to 0.8 V_{CC} | | V |
| $V_{ref(t)}$ | Input and output timing reference levels | 0.3 V_{CC} to 0.7 V_{CC} | | V |

Figure 15. AC test measurement I/O waveform

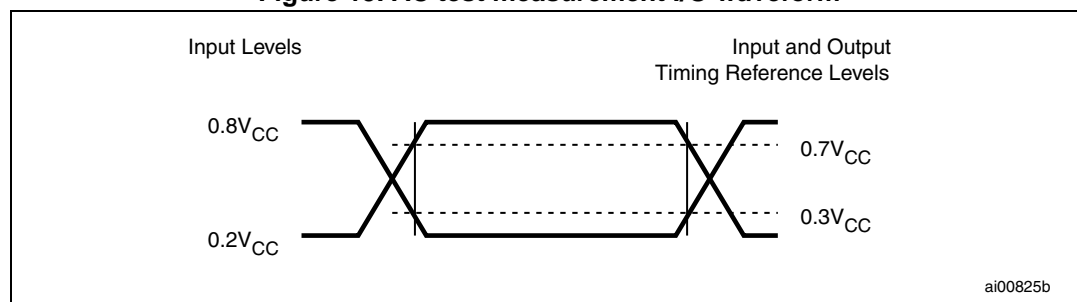


Table 73. Input parameters

| Symbol | Parameter | Min. | Max. | Unit |
|----------|---|------|------|------|
| C_{IN} | Input capacitance (SDA) | - | 8 | pF |
| C_{IN} | Input capacitance (other pins) | - | 6 | pF |
| t_{NS} | Pulse width ignored (Input filter on SCL and SDA) | - | 80 | ns |

Table 74. I²C DC characteristics

| Symbol | Parameter | Test condition | Min. | Max. | Unit |
|------------------|---|--|---------------------|---------------------|------|
| I _{LI} | Input leakage current (SCL, SDA) | V _{IN} = V _{SS} or V _{CC} device in Standby mode | - | ± 2 | μA |
| I _{LO} | Output leakage current | SDA in Hi-Z, external voltage applied on SDA: V _{SS} or V _{CC} | - | ± 2 | μA |
| I _{CC0} | Standby power mode supply current | V _{CC} = 3.3 V, with RF ON | - | 30 | μA |
| | | V _{CC} = 3.3 V, with RF OFF | - | 5 | |
| | | V _{CC} = 5.5 V, with RF ON | - | 30 | |
| | | V _{CC} = 5.5 V, with RF OFF | - | 5 | |
| I _{CC1} | Supply current (Session open) | V _{CC} = 3.3 V, with RF ON | - | 150 | μA |
| | | V _{CC} = 3.3 V, with RF OFF | - | 150 | |
| | | V _{CC} = 5.5 V, with RF ON | - | 150 | |
| | | V _{CC} = 5.5 V, with RF OFF | - | 150 | |
| I _{CC2} | Supply current ⁽¹⁾ (Read binary) | V _{CC} = 3.3 V (f _C = 1 MHz), with RF ON ⁽²⁾ | - | 250 | μA |
| | | V _{CC} = 3.3 V (f _C = 1 MHz), with RF OFF ⁽²⁾ | - | 200 | |
| | | V _{CC} = 5.5 V (f _C = 1 MHz), with RF ON ⁽²⁾ | - | 250 | |
| | | V _{CC} = 5.5 V (f _C = 1 MHz), with RF OFF ⁽²⁾ | - | 200 | |
| I _{CC3} | Supply current ⁽¹⁾ (Update binary) | V _{CC} = 3.3 V (f _C = 1 MHz), with RF ON ⁽²⁾ | - | 550 | μA |
| | | V _{CC} = 3.3 V (f _C = 1 MHz), with RF OFF ⁽²⁾ | - | 500 | |
| | | V _{CC} = 5.5 V (f _C = 1 MHz), with RF ON ⁽²⁾ | - | 550 | |
| | | V _{CC} = 5.5 V (f _C = 1 MHz), with RF OFF ⁽²⁾ | - | 500 | |
| V _{IL} | Input low voltage (SDA, SCL) | V _{CC} = 2.7 V V _{CC} = 5.5 V | -0.45 | 0.3 V _{CC} | V |
| V _{IH} | Input high voltage (SDA, SCL) | V _{CC} = 2.7 V V _{CC} = 5.5 V | 0.7 V _{CC} | 6.5 | V |
| V _{IL} | Input low voltage (RF disable) | V _{CC} = 2.7 V V _{CC} = 5.5 V | - | 0.45 | V |
| V _{IH} | Input high voltage (RF disable) | V _{CC} = 2.7 V V _{CC} = 5.5 V | 1.4 | - | V |
| V _{OL} | Output low voltage (SDA) | I _{OL} = 3 mA, V _{CC} = 5.5 V | - | 0.4 | V |
| | Output low voltage (GPO) | I _{OL} = 1 mA, V _{CC} = 2.7 to 5.5 V | - | 0.4 | V |

1. Characterized only.

2. Input levels as defined in [Figure 15](#).

Table 75. I²C AC characteristics (400 kHz)

| Test conditions specified in Table 71 (preliminary data based on design simulations) | | | | | |
|---|--------------|--|------|------|------|
| Symbol | Alt. | Parameter | Min. | Max. | Unit |
| f_C | f_{SCL} | Clock frequency | 0.05 | 400 | kHz |
| $t_{CHCL}^{(1)}$ | t_{HIGH} | Clock pulse width high | 600 | - | ns |
| $t_{CLCH}^{(2)}$ | t_{LOW} | Clock pulse width low | 1300 | - | ns |
| t_{XH1XH2} | t_R | Input signal rise time | (3) | (3) | ns |
| t_{XL1XL2} | t_F | Input signal fall time | (3) | (3) | ns |
| t_{DL1DL2} | t_F | SDA (out) fall time | 20 | 300 | ns |
| t_{DXCX} | $t_{SU:DAT}$ | Data in set up time | 100 | - | ns |
| t_{CLDX} | $t_{HD:DAT}$ | Data in hold time | 0 | - | ns |
| t_{CLQX} | t_{DH} | Data out hold time | 100 | - | ns |
| $t_{CLQV}^{(4)(5)}$ | t_{AA} | Clock low to next data valid (access time) | - | 900 | ns |
| $t_{CHDX}^{(6)}$ | $t_{SU:STA}$ | Start condition set up time | 600 | - | ns |
| t_{DLCL} | $t_{HD:STA}$ | Start condition hold time | 600 | - | ns |
| t_{CHDH} | $t_{SU:STO}$ | Stop condition set up time | 600 | - | ns |
| t_{DHDL} | t_{BUF} | Time between Stop condition and next Start condition | 1300 | - | ns |
| t_W | t_{WR} | I ² C write time in one page | - | 5 | ms |
| | | I ² C write time up to 246 bytes | - | 150 | ms |
| $t_{NS}^{(7)}$ | - | Pulse width ignored (input filter on SCL and SDA) | - | 80 | ns |

1. t_{CHCL} timeout.
2. t_{CLCH} timeout.
3. There is no min. or max. value for the input signal rise and fall times. It is however recommended by the I²C specification that the input signal rise and fall times be more than 20 ns and less than 300 ns when $f_C < 400$ kHz.
4. To avoid spurious Start and Stop conditions, a minimum delay is placed between SCL=1 and the falling or rising edge of SDA.
5. t_{CLQV} is the time (from the falling edge of SCL) required by the SDA bus line to reach 0.8V_{CC} in a compatible way with the I²C specification (which specifies $t_{SU:DAT}(\min) = 100$ ns), assuming that the $R_{bus} \times C_{bus}$ time constant is less than 500 ns (as specified in [Figure 17](#)).
6. For a reStart condition, or following a write cycle.
7. Characterized only, not tested in production.

Table 76. I²C AC characteristics (1 MHz)

| Test conditions specified in Table 71 (preliminary data based on design simulations) | | | | | |
|---|--------------|--|------|------|------|
| Symbol | Alt. | Parameter | Min. | Max. | Unit |
| f_C | f_{SCL} | Clock frequency | 0.05 | 1000 | kHz |
| $t_{CHCL}^{(1)}$ | t_{HIGH} | Clock pulse width high | 260 | - | ns |
| $t_{CLCH}^{(2)}$ | t_{LOW} | Clock pulse width low | 500 | - | ns |
| t_{XH1XH2} | t_R | Input signal rise time | (3) | (3) | ns |
| t_{XL1XL2} | t_F | Input signal fall time | (3) | (3) | ns |
| t_{DL1DL2} | t_F | SDA (out) fall time | 20 | 120 | ns |
| t_{DXCX} | $t_{SU:DAT}$ | Data in set up time | 50 | - | ns |
| t_{CLDX} | $t_{HD:DAT}$ | Data in hold time | 0 | - | ns |
| t_{CLQX} | t_{DH} | Data out hold time | 100 | - | ns |
| $t_{CLQV}^{(4)(5)}$ | t_{AA} | Clock low to next data valid (access time) | - | 450 | ns |
| $t_{CHDX}^{(6)}$ | $t_{SU:STA}$ | Start condition set up time | 250 | - | ns |
| t_{DLCL} | $t_{HD:STA}$ | Start condition hold time | 250 | - | ns |
| t_{CHDH} | $t_{SU:STO}$ | Stop condition set up time | 250 | - | ns |
| t_{DHDL} | t_{BUF} | Time between Stop condition and next Start condition | 500 | - | ns |
| t_W | t_{WR} | I ² C write time in one page | - | 5 | ms |
| | | I ² C write time up to 246 bytes | - | 150 | ms |
| $t_{NS}^{(7)}$ | - | Pulse width ignored (input filter on SCL and SDA) | - | 80 | ns |

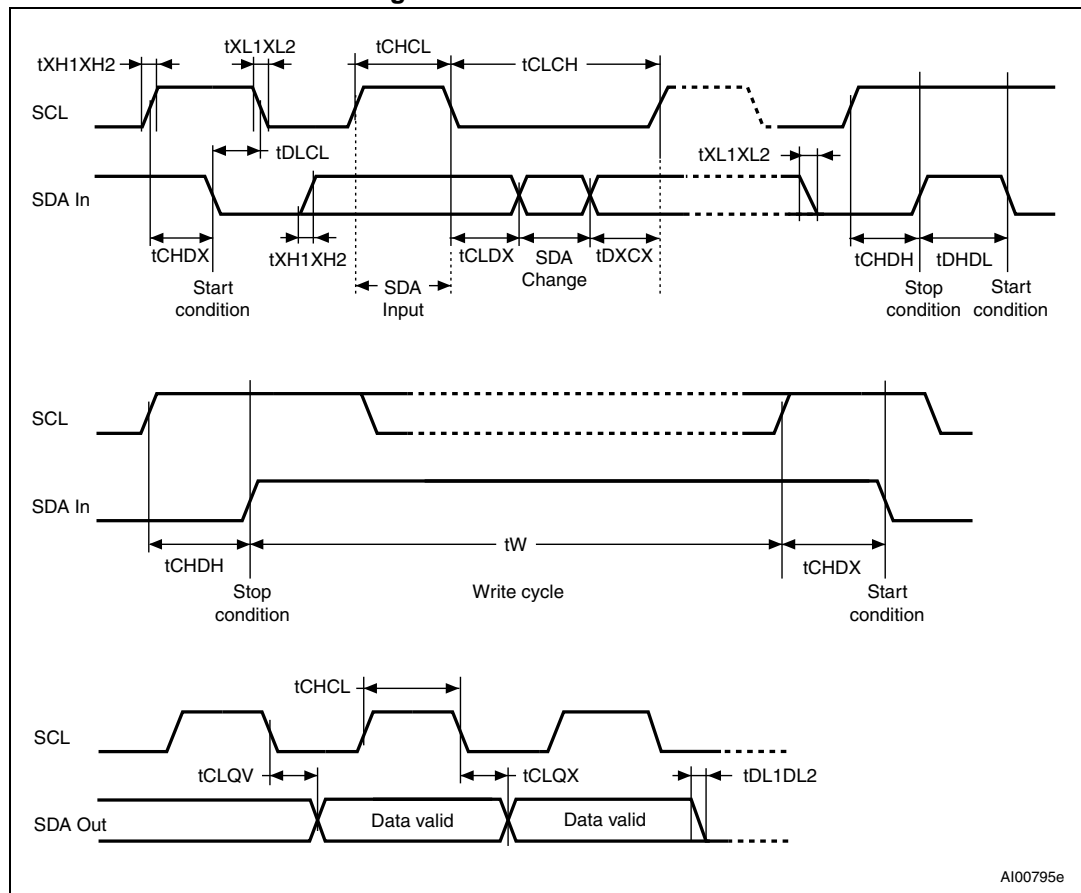
1. t_{CHCL} timeout.2. t_{CLCH} timeout.3. There is no min. or max. value for the input signal rise and fall times. It is however recommended by the I²C specification that the input signal rise and fall times be less than 120 ns when $f_C < 1$ MHz.

4. To avoid spurious Start and Stop conditions, a minimum delay is placed between SCL=1 and the falling or rising edge of SDA.

5. t_{CLQV} is the time (from the falling edge of SCL) required by the SDA bus line to reach $0.8V_{CC}$ in a compatible way with the I²C specification (which specifies $t_{SU:DAT}(\min) = 100$ ns), assuming that the $R_{bus} \times C_{bus}$ time constant is less than 500 ns (as specified in [Figure 17](#)).

6. For a reStart condition, or following a write cycle.

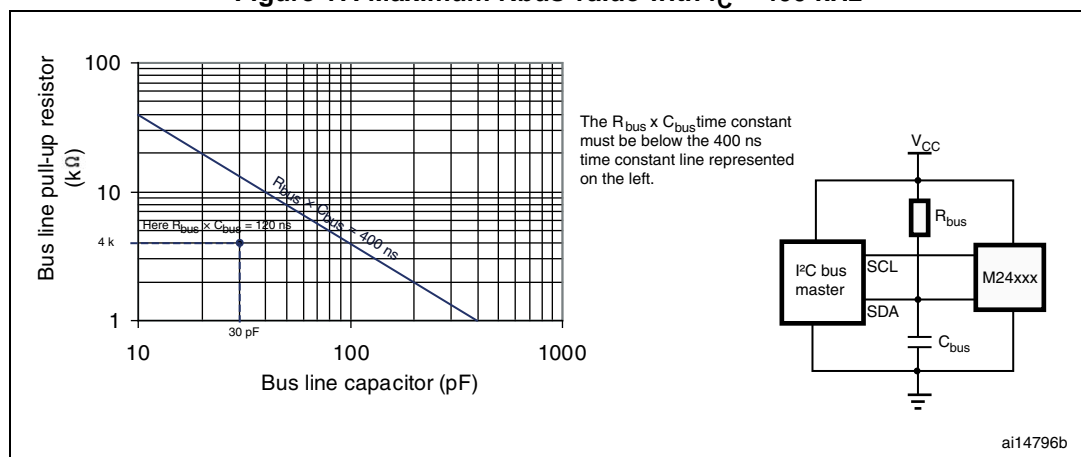
7. Characterized only, not tested in production.

Figure 16. I²C AC waveforms

AI00795e

11.1 I²C timing measurement condition

Figure 17 represents the Maximum R_{bus} value versus bus parasitic capacitance (C_{bus}) for an I²C bus at maximum frequency $f_C = 400$ kHz.

Figure 17. Maximum R_{bus} value with $f_C = 400$ kHz

ai14796b

Figure 18 represents the Maximum R_{bus} value versus bus parasitic capacitance (C_{bus}) for an I²C bus at maximum frequency $f_C = 1$ MHz.

Figure 18. Maximum R_{bus} value with $f_C = 1$ MHz

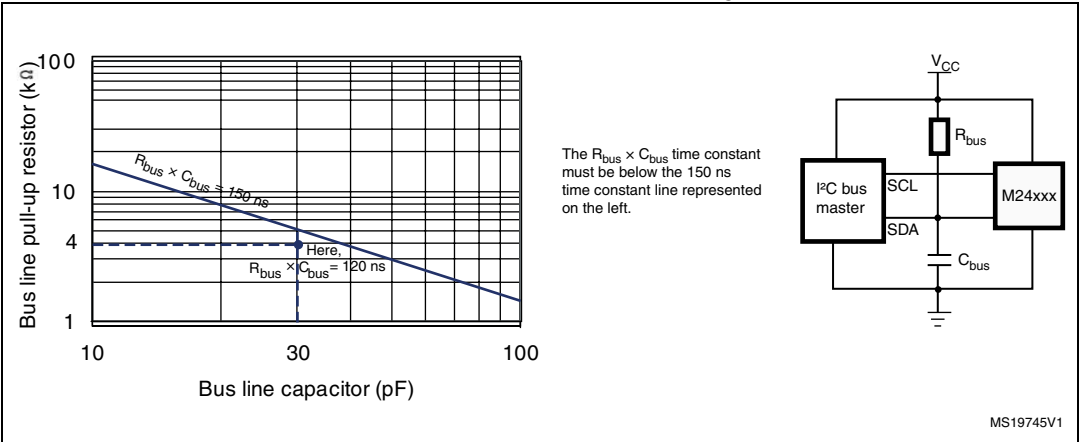


Figure 19. I²C bus protocol

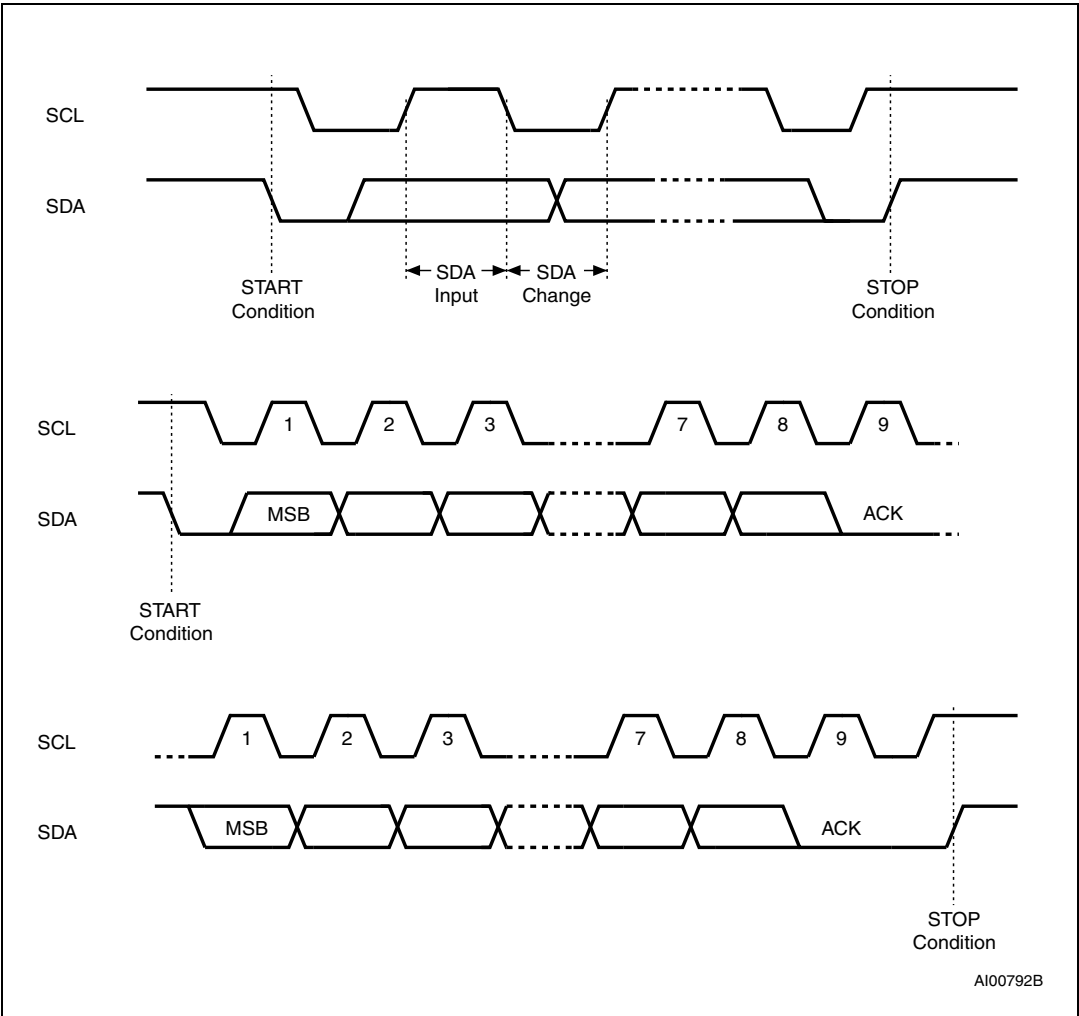


Table 77. Device select code

| | Device type identifier ⁽¹⁾ | | | | Chip Enable address | | | RW |
|--------------------|---------------------------------------|----|----|----|---------------------|----|----|----|
| | b7 | b6 | b5 | b4 | b3 | b2 | b1 | b0 |
| Device select code | 1 | 0 | 1 | 0 | 1 | 1 | 0 | RW |

1. The most significant bit, b7, is sent first.

12 GPO parameters

This section lists the timing of the GPO according to its configuration.

Table 78. GPO timings measurement ⁽¹⁾

| GPO field | | I/F | Condition | Command | Symbol | Typ. | Unit |
|---------------------|------|------------------|--|------------------------------|---|---------|----------|
| Session Open | 0xX1 | I ² C | GPO low when session active | Kill session | CmdSTPtoGPlow | 15* | μs |
| | | | | Get session | *add 100 μs for boot after POR | 15* | μs |
| | | I ² C | GPO return HZ | Deselect | AnswerlLBtoGPHZ | 105 | ns |
| | 0x1X | RF | GPO low when session active | NDEF select | CmdEOFtoGPlow | 170 | μs |
| | | RF | GPO return HZ | Deselect | CmdEOFtoGPHZ | 370 | μs |
| WIP | 0xX2 | I ² C | GPO low when programming | Update Binary | CmdSTPtoGPlow | 45 | μs |
| | | I ² C | | | Writing time duration (No time extension) | 5 | ms |
| | | RF | GPO low when programming | Update Binary | CmdEOFtoGPlow | 75 | μs |
| | 0x2X | RF | | | Writing time duration (No time extension) | 5 | ms |
| Answer Ready | 0xX3 | I ² C | GPO low when a command is computed | ReadBinary or UpdateBinary | CmdSTPtoGPlow | 55 or 5 | μs ms |
| | | I ² C | GPO return HZ on new command | All commands | After NewCmdlBFB or AnswerlBFB | 105 | ns |
| Message In Progress | 0x3X | RF | GPO low when modifying NDEF | UpdateBinary (Msg Length #0) | CmdEOFtoGPlow | 75 | μs |
| | | RF | GPO low when modifying NDEF | UpdateBinary | Writing time duration (No time extension) | 5 | ms |
| Interrupt | 0xX4 | I ² C | GPO low after receiving an Interrupt command | SendInterrupt | CmdSTPtoGPlow | 50 | μs |
| | | I ² C | GPO return HZ | All commands | After NewCmdlBFB or AnswerlBFB | 105 | ns |
| | 0x4X | RF | GPO low after receiving an Interrupt command | SendInterrupt | CmdEOFtoGPlow | 75 | μs |
| | | RF | | | Pulse duration | 540 | μs |

Table 78. GPO timings measurement ⁽¹⁾ (continued)

| GPO field | | I/F | Condition | Command | Symbol | Typ. | Unit |
|---------------|------|------------------|---|--|---------------|------|------|
| State Control | 0xX5 | I ² C | GPO low when reset | Reset GPO | CmdSTPtoGPlow | 40 | μs |
| | | I ² C | GPO return HZ when set | Set GPO | CmdSTPtoGPHZ | 40 | μs |
| | 0x5X | RF | GPO low when reset | Reset GPO | CmdEOFtoGPlow | 60 | μs |
| | | RF | GPO return HZ when set | Set GPO | CmdEOFtoGPHZ | 60 | μs |
| RF Busy | 0x6X | RF | GPO low after receiving an RF command | Anticollision command or start of RF disturb (command using another RF protocol) | CmdSOFtoGPlow | 6 | μs |
| | | RF | GPO return HZ after deselection or RF command in another protocol | Deselect or end of RF disturb (command using another RF protocol) | CmdEOFtoGPHZ | 460 | μs |

1. Characterized only.

13 RF electrical parameters

This section summarizes the operating and measurement conditions, and the DC and AC characteristics of the device in RF mode.

The parameters in the DC and AC characteristics tables that follow are derived from tests performed under the Measurement Conditions summarized in the relevant tables. Designers should check that the operating conditions in their circuit match the measurement conditions when relying on the quoted parameters.

Table 79. Default operating conditions

| Symbol | Parameter | Min. | Max. | Unit |
|--------|-------------------------------|------|------|------|
| T_A | Ambient operating temperature | -40 | 85 | °C |

Table 80. RF characteristics ⁽¹⁾

| Symbol | Parameter | Condition | Min | Typ | Max | Unit |
|----------------|--|---------------------------------------|------------------|-------|------------|------|
| f_C | External RF signal frequency | | 13.553 | 13.56 | 13.567 | MHz |
| H_{ISO} | Operating field according to ISO | $T_A = 0\text{ °C to }50\text{ °C}$ | 1500 | - | 7500 | mA/m |
| $H_{Extended}$ | Operating field in extended temperature range | $T_A = -40\text{ °C to }85\text{ °C}$ | 500 | - | 7500 | mA/m |
| $MI_{CARRIER}$ | 100% carrier modulation index | $MI = (A-B)/(A+B)$ | 90 | - | 100 | % |
| t_1 | Pause A length | - | $28/f_C$ | - | $40.5/f_C$ | μs |
| t_2 | Pause A low time | - | $7/f_C$ | - | t_1 | μs |
| t_3 | Pause A rise time | - | $1.5 \times t_4$ | - | $16/f_C$ | μs |
| t_4 | Pause A rise time section | - | 0 | - | $6/f_C$ | μs |
| $t_{MIN\ CD}$ | Minimum time from carrier generation to first data | From H-field min | - | - | 5 | ms |
| W_t | RF write time (including internal Verify) for one page | - | - | 6 | - | ms |
| C_{TUN} | Internal tuning capacitor in SO8 ⁽²⁾ | $f_C = 13.56\text{ MHz}$ | 22.5 | 25 | 27.5 | pF |
| t_{RF_OFF} | RF OFF time | Chip reset | - | - | 5 | ms |

- All timing characterizations were performed on a reference antenna with the following characteristics:
 External size: 75 mm x 48 mm
 Number of turns: 6
 Width of conductor: 0.6 mm
 Space between two conductors: 0.6 mm
 Value of the tuning capacitor in SO8: 25 pF (M24SR64-Y)
 Value of the coil: 5 μH
 Tuning frequency: 14.2 MHz.
- Characterized only, at room temperature only, measured at VAC0-VAC1 = 2 V peak to peak at 13.56 MHz.

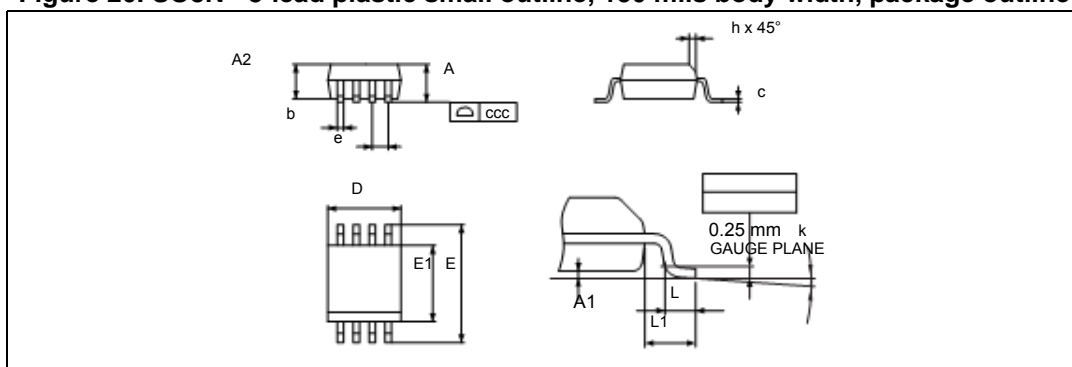
14 Package mechanical data

In order to meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at: www.st.com.

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14.1 Mechanical data for the SO8N package

Figure 20. SO8N - 8-lead plastic small outline, 150 mils body width, package outline



1. Drawing is not to scale.

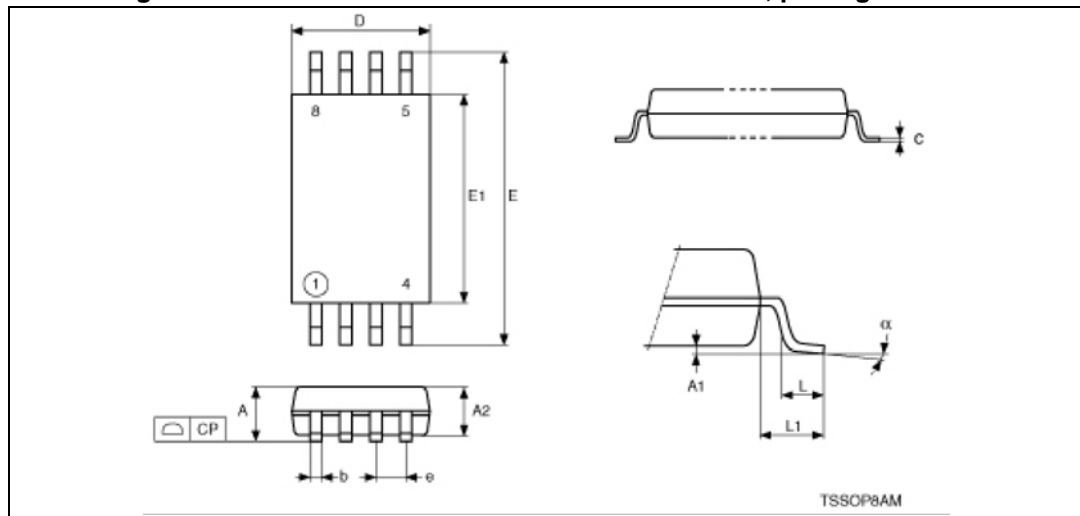
Table 81. SO8N - 8-lead plastic small outline, 150 mils body width, package data

| Symbol | millimeters | | | inches ⁽¹⁾ | | |
|--------|-------------|-------|-------|-----------------------|--------|--------|
| | Typ | Min | Max | Typ | Min | Max |
| A | - | - | 1.750 | - | - | 0.0689 |
| A1 | - | 0.100 | 0.250 | - | 0.0039 | 0.0098 |
| A2 | - | 1.250 | | - | 0.0492 | |
| b | - | 0.280 | 0.480 | - | 0.0110 | 0.0189 |
| c | - | 0.170 | 0.230 | - | 0.0067 | 0.0091 |
| ccc | - | - | 0.100 | - | - | 0.0039 |
| D | 4.900 | 4.800 | 5.000 | 0.1929 | 0.1890 | 0.1969 |
| E | 6.000 | 5.800 | 6.200 | 0.2362 | 0.2283 | 0.2441 |
| E1 | 3.900 | 3.800 | 4.000 | 0.1535 | 0.1496 | 0.1575 |
| e | 1.270 | - | - | 0.0500 | - | - |
| h | - | 0.250 | 0.500 | - | - | - |
| k | - | 0° | 8° | - | 0° | 8° |
| L | - | 0.400 | 1.270 | - | 0.0157 | 0.0500 |
| L1 | 1.04 | - | - | 0.0410 | - | - |

1. Values in inches are converted from mm and rounded to 4 decimal digits.

14.2 Mechanical data for the TSSOP8 package

Figure 21. TSSOP8 - 8-lead thin shrink small outline, package outline



1. Drawing is not to scale.

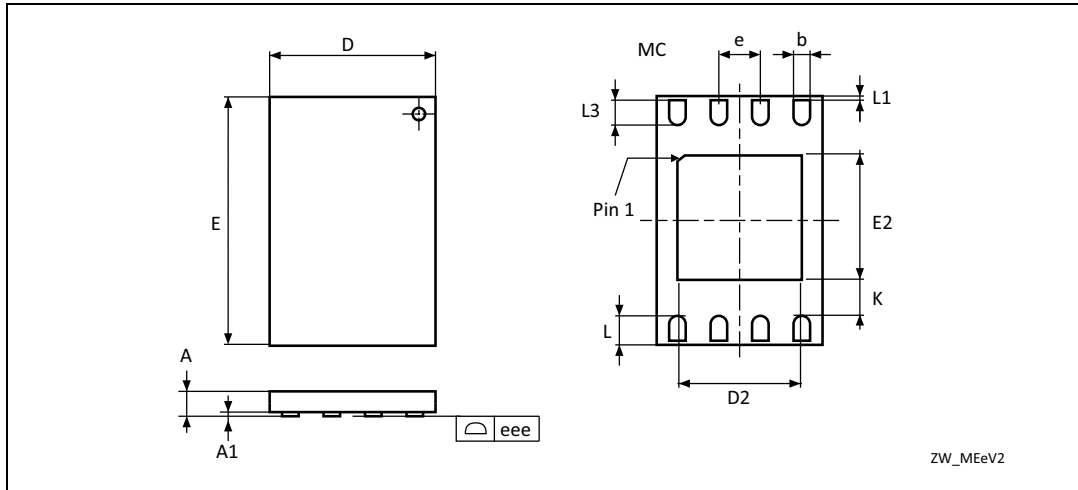
Table 82. TSSOP8 - 8-lead thin shrink small outline, 169 mils width, package data

| Symbol | millimeters | | | inches ⁽¹⁾ | | |
|--------|-------------|-------|-------|-----------------------|--------|--------|
| | Typ | Min | Max | Typ | Min | Max |
| A | - | - | 1.200 | - | - | 0.0472 |
| A1 | - | 0.050 | 0.150 | - | 0.0020 | 0.0059 |
| A2 | 1.000 | 1.800 | 1.050 | 0.0394 | 0.0315 | 0.0413 |
| b | - | 0.190 | 0.300 | - | 0.0075 | 0.0118 |
| c | - | 0.090 | 0.200 | - | 0.0035 | 0.0079 |
| CP | - | - | 0.100 | - | - | 0.0039 |
| D | 3.000 | 2.900 | 3.100 | 0.1181 | 0.1142 | 0.1220 |
| e | 0.650 | - | - | 0.0256 | - | - |
| E | 6.400 | 6.200 | 6.600 | 0.2520 | 0.2441 | 0.2598 |
| E1 | 4.400 | 4.300 | 4.500 | 0.1732 | 0.1693 | 0.1772 |
| L | 0.600 | 0.450 | 0.750 | 0.02636 | 0.0177 | 0.0295 |
| L1 | 1.000 | - | - | 0.0394 | - | - |
| a | | 0° | 8° | | 0° | 8° |
| N | 8 | | | 8 | | |

1. Values in inches are converted from mm and rounded to 4 decimal digits.

14.3 Mechanical data for the UFDFPN8 package

Figure 22. UFDFPN8 - 8-lead ultra thin fine pitch dual flat package, no lead, 2x3 mm, package outline



1. Drawing is not to scale.
2. The central pad (area E2 by D2 in the above illustration) is internally pulled to V_{SS} . It must not be connected to any other voltage or signal line on the PCB, for example during the soldering process.

Table 83. UFDFPN8 - 8-lead ultra thin fine pitch dual flat package, no lead, package data

| Symbol | millimeters | | | inches ⁽¹⁾ | | |
|--------------------|-------------|-------|-------|-----------------------|--------|--------|
| | Typ | Min | Max | Typ | Min | Max |
| A | 0.550 | 0.450 | 0.600 | 0.0217 | 0.0177 | 0.0236 |
| A1 | 0.020 | 0.000 | 0.050 | 0.0008 | 0.0000 | 0.0020 |
| b | 0.250 | 0.200 | 0.300 | 0.0098 | 0.0079 | 0.0118 |
| D | 2.000 | 1.900 | 2.100 | 0.0787 | 0.0748 | 0.0827 |
| D2 (rev MC) | - | 1.200 | 1.600 | - | 0.0472 | 0.0630 |
| E | 3.000 | 2.900 | 3.100 | 0.1181 | 0.1142 | 0.1220 |
| E2 (rev MC) | - | 1.200 | 1.600 | - | 0.0472 | 0.0630 |
| e | 0.500 | - | - | 0.0197 | - | - |
| K (rev MC) | - | 0.300 | - | - | 0.0118 | - |
| L | - | 0.300 | 0.500 | - | 0.0118 | 0.0197 |
| L1 | - | - | 0.150 | - | - | 0.0059 |
| L3 | - | 0.300 | - | - | 0.0118 | - |
| eee ⁽²⁾ | - | 0.080 | - | - | 0.0031 | - |

1. Values in inches are converted from mm and rounded to 4 decimal digits.
2. Applied for exposed die paddle and terminals. Exclude embedded part of exposed die paddle from measuring.

15 Part numbering

Table 84. Ordering information scheme for packaged devices

| | | | | | | | |
|--|-----|----|-------|----|---|---|----|
| Example: | M24 | SR | 64- Y | MN | 6 | T | /2 |
| Device type | | | | | | | |
| M24 = I ² C interface device | | | | | | | |
| Device feature | | | | | | | |
| SR = Short range | | | | | | | |
| Memory size | | | | | | | |
| 64 = memory size in Kbits | | | | | | | |
| Voltage range | | | | | | | |
| Y = 2.7 to 5.5 V | | | | | | | |
| Package | | | | | | | |
| MN = SO8N | | | | | | | |
| DW = TSSOP8 | | | | | | | |
| MC = UFDFPN8 | | | | | | | |
| SB12I = 120 µm ± 15 µm bumped and sawn inkless wafer on 8-inch frame | | | | | | | |
| Device grade | | | | | | | |
| 6 = industrial: device tested with standard test flow over -40 to 85 °C (No parameter for SB12I) | | | | | | | |
| Option | | | | | | | |
| T = Tape and reel packing (No parameter for SB12I) | | | | | | | |
| Capacitance | | | | | | | |
| /2 = 25 pF | | | | | | | |

16 Revision history

Table 85. Document revision history

| Date | Revision | Changes |
|-------------|----------|--|
| 15-Jan-2013 | 1 | Initial release. |
| 12-Apr-2013 | 2 | Global contents update. |
| 16-May-2013 | 3 | Global contents update. |
| 17-May-2013 | 4 | Updated “Number of bytes in CC file” value and comment in Table 4: CC file layout for 1 NDEF file . Added Table 75: I2C AC characteristics (400 kHz) and Table 76: I2C AC characteristics (1 MHz) . |
| 21-Jun-2013 | 5 | Added missing “TSSOP 8” below the second figure on page 1 . Removed a sentence in Section 1: Functional description and updated a sentence in Section 2.5: Supply voltage (VCC) . Updated Section 2.7: General purpose output (GPO) including all graphics. Updated Section 3.1.2: CC file layout and Section 3.2: Read and write access rights to the memory , Section 4.1: Master and slave , Section 4.2.2: I2C token , Section 5.5: CRC of the I2C and RF frame . Added rows to Table 6: Field list . Added a note to , updated Table 8: Details about the RF Session field and Table 10: Details about the RF enable field . Updated Figure 1: See the procedure to lock the write access . and added a note below Figure 12: Command and response exchange . Updated or added text to Section 5.7.1: Verify command to Section 5.7.4: Disable Verification Requirement command , Section 8.7: Changing an NDEF password procedure Updated Table 60: Ascending and descending data rate coding . Added Section 5.8: ST Proprietary command set , Section 5.10: Specific I2C command set and Section 6: RF device operation Changed “GetRFsession command into “GetI2Csession command”, and “Detection of an NDEF message” into “Selection of an NDEF message”. Updated ICCs in Table 74: I2C DC characteristics . Removed “ASK modulated signal” figure and text before from Section 13: RF electrical parameters . |

Table 85. Document revision history (continued)

| Date | Revision | Changes |
|-------------|----------|---|
| 29-Aug-2013 | 6 | <p>Added UDFPN8 drawing on page 1.</p> <p>Changed “dual interface device”, “dual interface EEPROM” and “dual interface memory” into “NFC dynamic tag device”.</p> <p>Changed “EnablePermanentSecurity” into “EnablePermanentState” in Table 13: RF and I²C command sets.</p> <p>Updated the bitfields in Table 15, Table 19, Table 21, Table 56, Table 59 and Table 65.</p> <p>Changed the following commands:</p> <ul style="list-style-type: none"> – “ReadMemory” into “STReadMemory”, – “Read binary” into “STReadBinary”, – “EnablePermanentLock” into “EnablePermanentState”. <p>Updated I_{CC0} parameter in Table 74: I²C DC characteristics and added a note.</p> <p>Added Section 14.3: Mechanical data for the UDFPN8 package and UDFPN8 package.</p> |
| 08-Nov-2013 | 7 | Global changes. |
| 12-Dec-2013 | 8 | <p>Restored the whole content of Table 74: I²C DC characteristics.</p> <p>Updated the capacitor values in Section 2.5.1: Operating supply voltage VCC.</p> <p>Removed bullet (4) from Section 8.6: Reaching the read-only state for an NDEF file.</p> <p>Updated V_{ESD} value in Table 70: Absolute maximum ratings, I_{CC} values in Table 74: I²C DC characteristics, and H_Extended value in Table 80: RF characteristics.</p> <p>Added details to “S(WTX)” bullet in Section 5.4: S-Block format.</p> <p>Added sentences to Section 5.6.8: UpdateBinary command and to Section 5.8.3: DisablePermanentState command.</p> <p>Changed ‘0x001E’ value into ‘0x001F’ in Table 53: StateControl command format.</p> <p>Updated values in Table 58: ATS response.</p> |
| 18-Dec-2013 | 9 | <p>Changed the datasheet status from “Preliminary data” to “Production data”.</p> <p>Added Note (4) to Figure 10: Changing the read access right to an NDEF file and Figure 11: Changing the write access right to an NDEF file.</p> |

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