

High Accuracy Ambient Light Sensor With I²C Interface



LINKS TO ADDITIONAL RESOURCES



DESCRIPTION

VEML4031X00 is a high accuracy ambient light digital 16-bit resolution sensor in a miniature opaque 4.38 mm x 1.45 mm package. It includes a high sensitive photodiode, a low noise amplifier, a 16-bit A/D converter and supports an easy to use I²C bus communication interface and additional interrupt feature.

Pin FMEA is provided by request; supports functional safety integration at customer level.

FEATURES

- Package type: surface-mount
- Dimensions (L x W x H in mm): 4.38 x 1.45 x 0.6
- AEC-Q100 qualified
- Integrated modules: ambient light sensor (ALS)
- Supply voltage range V_{DD} : 2.5 V to 3.6 V
- Communication via I²C interface
- Floor life: 4 weeks, MSL 2a, according to J-STD-020
- Low shut down current consumption: typ. 0.5 μ A
- Material categorization: for definitions of compliance please see www.vishay.com/doc?99912



APPLICATIONS

Ambient light sensor in automotive for

- Display backlight controls
- Infotainment systems
- Rear view mirror dimming
- Interior lighting control systems
- [Head-up displays](#)

PRODUCT SUMMARY

PART NUMBER	OPERATING VOLTAGE RANGE (V)	I ² C BUS VOLTAGE RANGE (V)	AMBIENT LIGHT RANGE (lx)	AMBIENT LIGHT RESOLUTION (lx)	OUTPUT CODE	ADC RESOLUTION PROXIMITY / AMBIENT LIGHT
VEML4031X00	2.5 to 3.6	1.7 to 3.6	0 to 172 000	0.0026	16 bit, I ² C	- / 16 bit

ORDERING INFORMATION

ORDERING CODE	PACKAGING	VOLUME ⁽¹⁾
VEML4031X00	Tape and reel	MOQ: 4500
VEML40311X00	Tape and reel	MOQ: 4500

Note

⁽¹⁾ MOQ: minimum order quantity

SLAVE ADDRESS OPTIONS

ORDERING CODE	SLAVE ADDRESS (7 bit)
VEML4031X00	0x29
VEML40311X00	0x10

**ABSOLUTE MAXIMUM RATINGS** ($T_{amb} = 25\text{ }^{\circ}\text{C}$, unless otherwise specified)

PARAMETER	TEST CONDITION	SYMBOL	MIN.	MAX.	UNIT
Supply voltage		V_{DD}	0	3.6	V
Operation temperature range		T_{amb}	-40	+110	$^{\circ}\text{C}$
Storage temperature range		T_{stg}	-40	+110	$^{\circ}\text{C}$
Total power dissipation	$T_{amb} \leq 25\text{ }^{\circ}\text{C}$	P_{tot}	-	50	mW
Junction temperature		T_j	-	+110	$^{\circ}\text{C}$

BASIC CHARACTERISTICS ($T_{amb} = 25\text{ }^{\circ}\text{C}$, unless otherwise specified)

PARAMETER	TEST CONDITION	SYMBOL	MIN.	TYP.	MAX.	UNIT
Supply voltage		V_{DD}	2.5	3.3	3.6	V
Supply current	Shutdown state ⁽¹⁾ ; $V_{DD} = V_{BUS}$	I_{DD}	-	0.5	-	μA
	Shutdown state ⁽¹⁾ ; $V_{DD} = V_{BUS} = 3.0\text{ V}$		-	-	1.2	
	Shutdown state ⁽¹⁾ ; $V_{DD} = 3.6\text{ V}$, $V_{BUS} = 1.7\text{ V}$		-	3.1	-	
	Active state; $V_{DD} = 3.3\text{ V}$		-	280	-	
I ² C clock rate range		f_{SCL}	10	-	400	kHz
I ² C bus input H-level range	$V_{BUS} = V_{DD}$	V_{ih}	$0.7 \times V_{BUS}$	-	3.6	V
	$V_{BUS} \neq V_{DD}$	V_{ih}	$0.85 \times V_{BUS}$	-	3.6	V
I ² C bus input L-level range	$V_{BUS} = V_{DD}$	V_{il}	-0.3	-	$0.3 \times V_{BUS}$	V
	$V_{BUS} \neq V_{DD}$	V_{il}	-0.3	-	$0.2 \times V_{BUS}$	V
Digital current out (low, current sink)		I_{ol}	3	-	-	mA
Digital resolution (LSB count) ⁽²⁾	With $ALS_GAIN = \times 2$, $ALS_IT = 400\text{ ms}$, $ALS_PDDIV = 4/4\text{ PD}$		-	0.0026	-	lx/step
Detectable maximum illuminance	With $ALS_GAIN = \times 0.5$, $ALS_IT = 6.25\text{ ms}$, $ALS_PDDIV = 1/4\text{ PD}$	$E_{V\text{ max.}}$	-	172 000	-	lx
Dark offset ⁽²⁾	With $ALS_GAIN = \times 2$, $ALS_IT = 200\text{ ms}$, $ALS_PDDIV = 4/4\text{ PD}$	ALS	-	4	-	step
		IR	-	4	-	

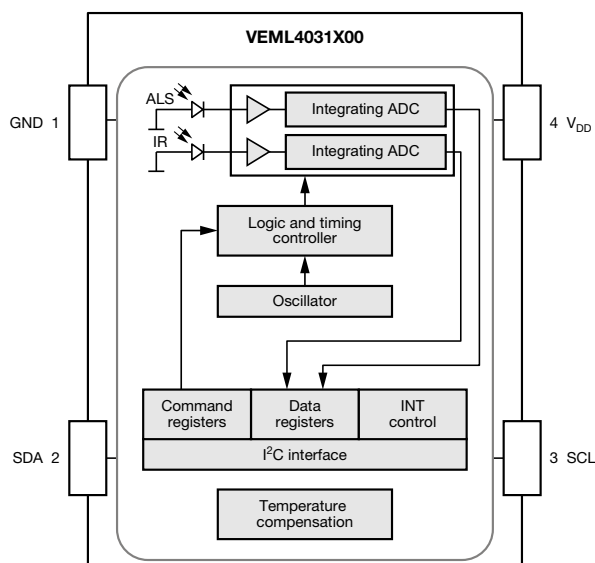
Notes⁽¹⁾ Light conditions: dark⁽²⁾ Light conditions: $E_v = 100\text{ lx}$ with 4300K white LED**CIRCUIT BLOCK DIAGRAM**

Fig. 1 - Block Diagram

I²C TIMING CHARACTERISTICS ($T_{amb} = 25^{\circ}\text{C}$, unless otherwise specified)						
PARAMETER	SYMBOL	STANDARD MODE ⁽¹⁾		FAST MODE ⁽¹⁾		UNIT
		MIN.	MAX.	MIN.	MAX.	
Clock frequency	$f_{(SMBCLK)}$	10	100	10	400	kHz
Bus free time between start and stop condition	$t_{(BUF)}$	4.7	-	1.3	-	μs
Hold time after (repeated) start condition; after this period, the first clock is generated	$t_{(HDSTA)}$	4.0	-	0.6	-	μs
Repeated start condition setup time	$t_{(SUSTA)}$	4.7	-	0.6	-	μs
Stop condition setup time	$t_{(SUSTO)}$	4.0	-	0.6	-	μs
Data hold time	$t_{(HDDAT)}$	0	3450	0	900	ns
Data setup time	$t_{(SUDAT)}$	250	-	100	-	ns
I ² C clock (SCK) low period	$t_{(LOW)}$	4.7	-	1.3	-	μs
I ² C clock (SCK) high period	$t_{(HIGH)}$	4.0	-	0.6	-	μs
Detect clock / data low timeout	$t_{(TIMEOUT)}$	25	35	-	-	ms
Clock / data fall time	$t_{(F)}$	-	300	-	300	ns
Clock / data rise time	$t_{(R)}$	-	1000	-	300	ns

Note

(1) Data based on standard I²C protocol requirement, not tested in production

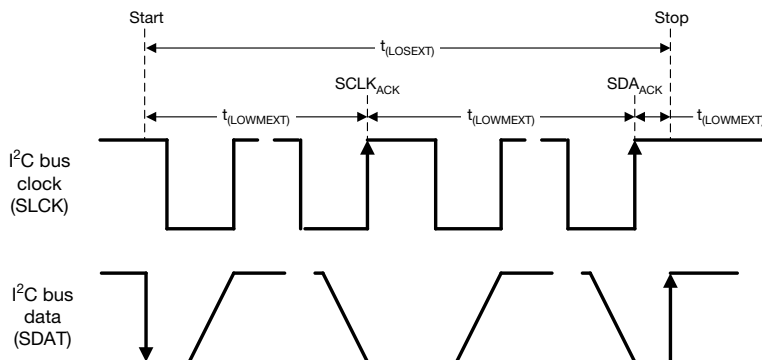
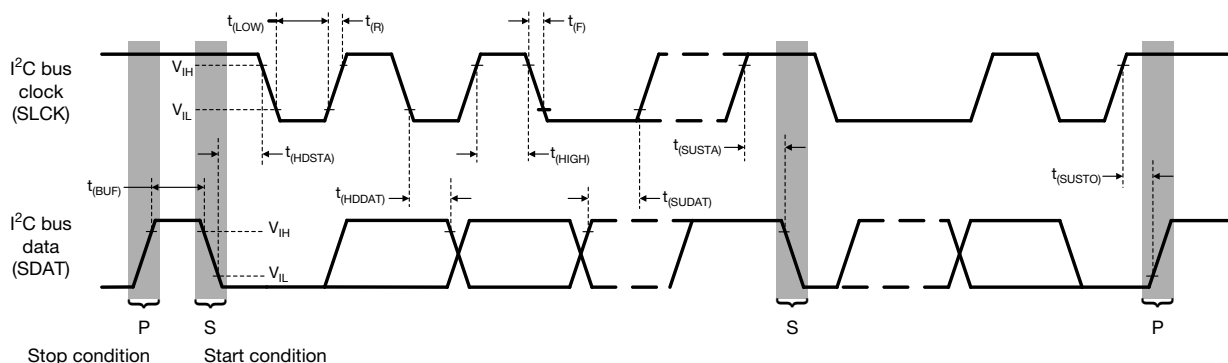


Fig. 2 - I²C Timing Diagram



PARAMETER TIMING INFORMATION

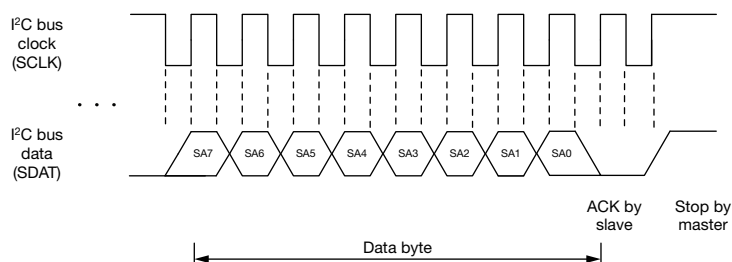
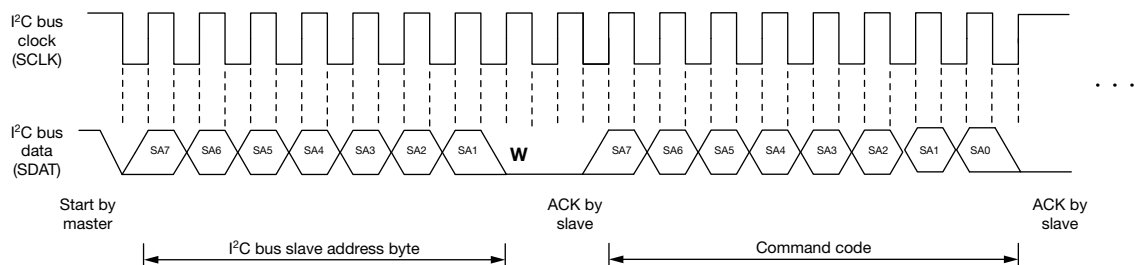


Fig. 3 - I2C Bus Timing for Sending Word Command Format

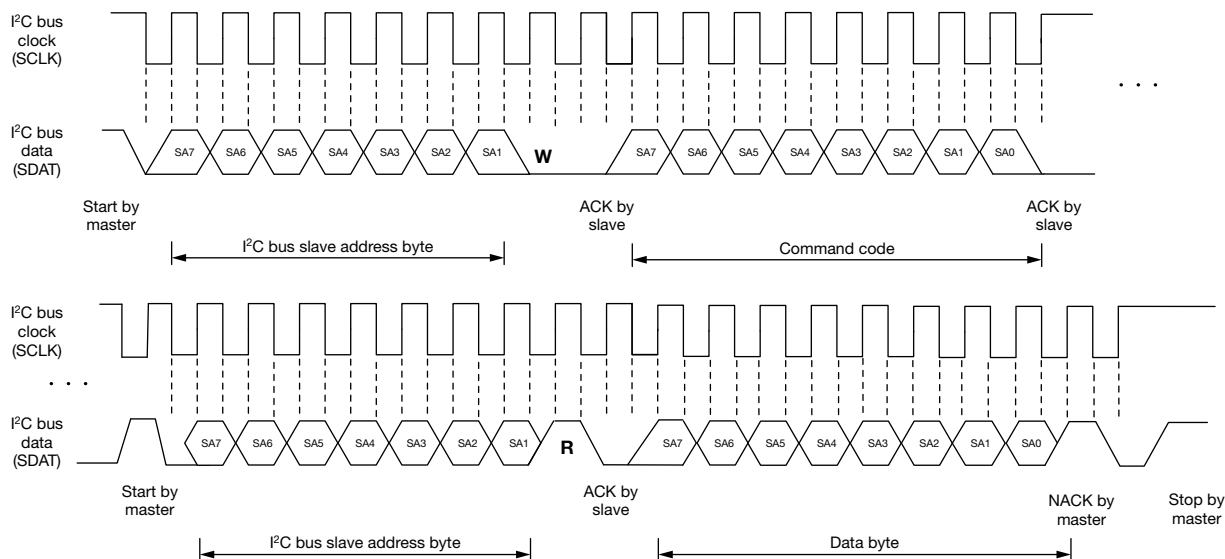


Fig. 4 - I2C Bus Timing for Receive Word Command Format

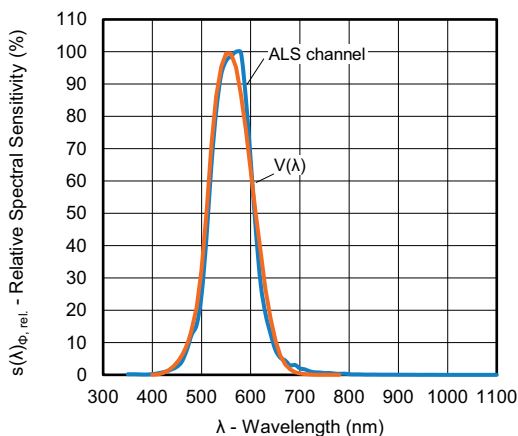
BASIC CHARACTERISTICS ($T_{amb} = 25\text{ }^{\circ}\text{C}$, unless otherwise specified)


Fig. 5 - Relative Spectral Sensitivity ALS Channel vs. Wavelength

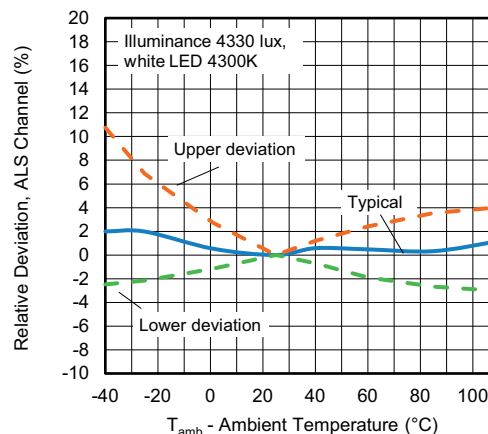


Fig. 8 - Relative Deviation ALS Channel vs. Ambient Temperature (at lux levels lower than ~200 lux, dark current effects should be taken into account)

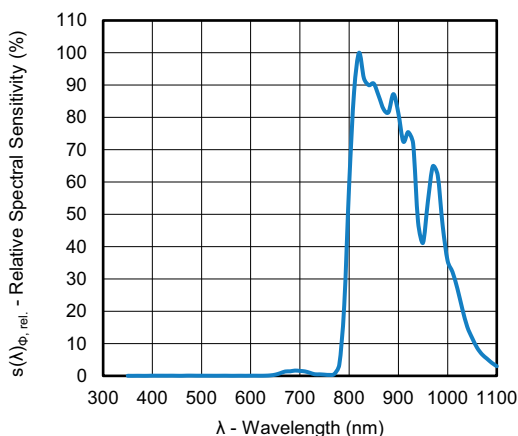


Fig. 6 - Relative Spectral Sensitivity IR Channel vs. Wavelength

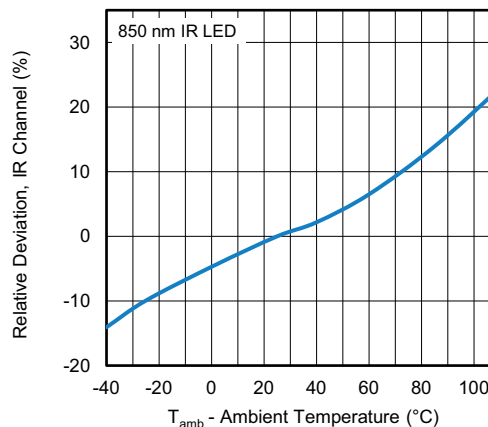


Fig. 9 - Relative Deviation IR Channel vs. Ambient Temperature

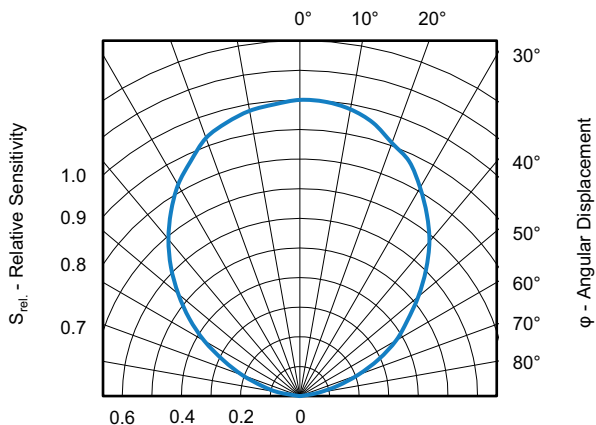


Fig. 7 - Relative Sensitivity vs. Angular Displacement

APPLICATION INFORMATION

1. Application Circuit

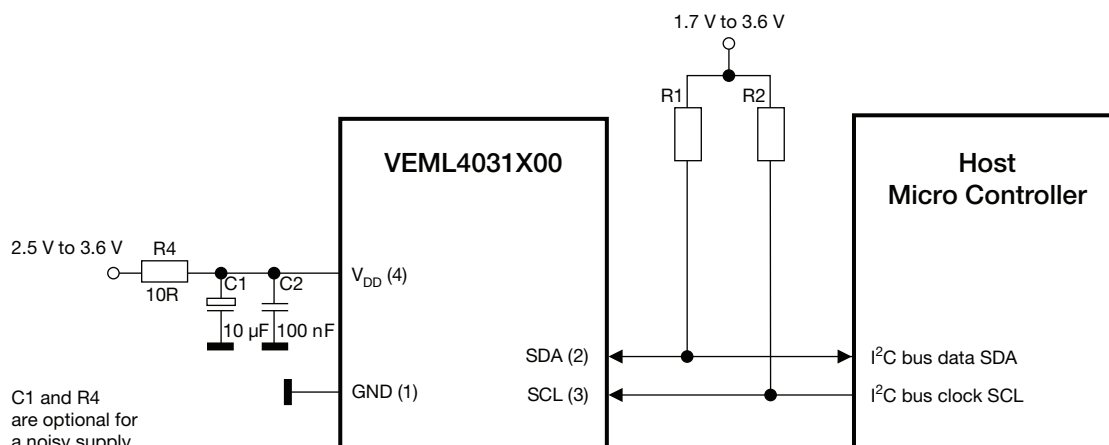


Fig. 10 - Application Circuit
(x) = Pin Number

Notes

- The interrupt pin is an open drain output. Proposed values for the pull-up resistors should be $> 1 \text{ k}\Omega$, e.g. $2.2 \text{ k}\Omega$ to $4.7 \text{ k}\Omega$ for the R1 and R2 (at SDA and SCL) and $10 \text{ k}\Omega$ to $100 \text{ k}\Omega$ for R3 (at interrupt). Normally just one decoupling capacitor is needed. This should be $\geq 100 \text{ nF}$ and placed close to the V_{DD} pin.

For detailed description about set-up and use of the interrupt as well as more application related information see AN: "Designing VEML4031X00 into an Application"

2. I²C Interface

The VEML4031X00 has eighteen register addresses responsible for operation control, parameter setup and result buffering. All registers are accessible via I²C communication. Fig. 9 shows the basic I²C communication with VEML4031X00.

The built in I²C interface is compatible with I²C modes "standard" and "fast": 10 kHz to 400 kHz.

Please refer to the I²C specification from NXP for details.

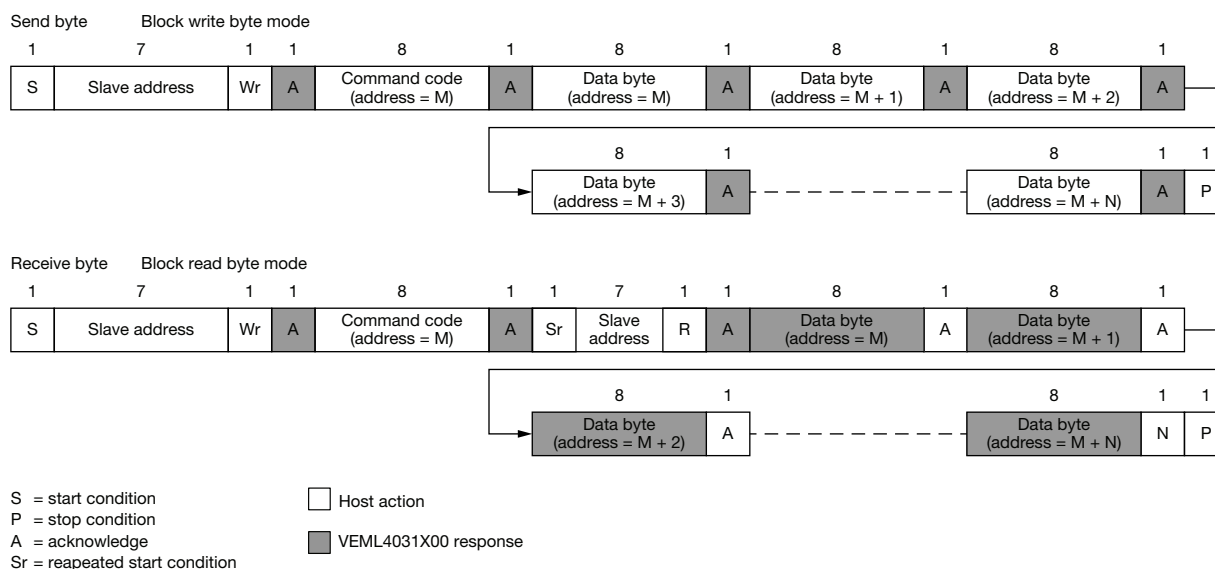


Fig. 11 - Send Byte / Receive Byte Protocol

**REGISTER INFORMATION****Device Address**

The VEML4031X00 is available in two different pre-configured slave addresses. For one version the predefined 7 bit I²C bus address is set to 0101001 = 0x29. The least significant bit (LSB) defines read or write mode. Accordingly the bus address is set to 0101 0010 = 0x52 for write and 0101 0011 = 0x53 for read. The second version comes with predefined 7 bit I²C bus address of 0010000 = 0x10, so, here the write address is 0010 0000 = 0x20 for write and 0010 0001 = 0x21 for read.

TABLE 1 - SLAVE ADDRESS TABLE

ORDERING CODE	7 BIT SLAVE ADDRESS	8 BIT SLAVE ADDRESS	
VEML4031X00	0x29	0x52 (Write)	0x53 (Read)
VEML40311X00	0x10	0x20 (Write)	0x21 (Read)

Register Addresses

The VEML4031X00 has eighteen registers, accessible through their respective 8-bit command codes.

Note that due to the location of the two shutdown bits (ALS_ON_0 and ALS_ON_1), one in register 0x00 and the other in 0x01, it is necessary to always write to both registers at once when configuring the device.

Auto-Memorization

The VEML4031X00 stores the last measured ambient data before the device is shutdown, keeping the data accessible.

When VEML4031X00 is in shutdown mode, the host can freely read this data via read command directly.

When VEML4031X00 wakes up, the data will be refreshed once a new measurement is made.

TABLE 2 - COMMAND CODE AND REGISTER DESCRIPTION

COMMAND CODE	DATA BYTE LOW / HIGH	REGISTER NAME	DEFAULT VALUE	FUNCTION	ACCESS
0x00	-	ALS_CONF_0	0x01	Set the integration time	Write and read
				Measurement mode of the sensor	
				Enable interrupt function of the ALS channel	
				Switch the sensor on / off	
0x01	-	ALS_CONF_1	0x80	Switch the sensor on / off	
				GAIN and photodiode size setting	
				Interrupt persistence counter	
0x04	Low	ALS_THDH_L	0x00	ALS channel high threshold window setting (low byte)	
0x05	High	ALS_THDH_H	0x00	ALS channel high threshold window setting (high byte)	
0x06	Low	ALS_THDL_L	0x00	ALS channel low threshold window setting (low byte)	
0x07	High	ALS_THDL_H	0x00	ALS channel low threshold window setting (high byte)	
0x10	Low	ALS_DATA_L	0x00	Low byte of 16-bit ALS channel result data	Read only
0x11	High	ALS_DATA_H	0x00	High byte of 16-bit ALS channel result data	
0x12	Low	IR_DATA_L	0x00	Low byte of 16-bit IR channel result data	
0x13	High	IR_DATA_H	0x00	High byte of 16-bit IR channel result data	
0x14	Low	VEML4031X00_ID_L	0x01	ID code	
0x15	High	VEML4031X00_ID_H	0x00	ID code	
0x16	Low	INT_FLAG	0x00	Reserved	
0x17	High	INT_FLAG	0x00	Interrupt and active force mode event flag	

Notes

- Command code 0x00 default value is 0x01 = device is shutdown
- Command 0x00 and command 0x01 must be executed together, they cannot be executed independently

**TABLE 3 - REGISTER NAME: ALS_CONF_0**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Reserved	ALS_IT			ALS_MODE	ALS_TRIG	ALS_INT	ALS_ON_0
COMMAND CODE					0x00		
BIT NAME		FUNCTION		BIT	VALUE	DESCRIPTION	
Reserved		Reserved		7	0x0 (0b0)	Should be kept default	
ALS_IT		Set the integration time		6 : 4	0x0 (0b000)	3.125 ms (default)	
					0x1 (0b001)	6.25 ms	
					0x2 (0b010)	12.5 ms	
					0x3 (0b011)	25 ms	
					0x4 (0b100)	50 ms	
					0x5 (0b101)	100 ms	
					0x6 (0b110)	200 ms	
					0x7 (0b111)	400 ms	
ALS_MODE		Set the measurement mode of the sensor		3	0x0 (0b0)	Auto mode (default)	
					0x1 (0b1)	Active force mode	
ALS_TRIG		Set the active force mode trigger; this bit will be reset to 0 after the measurement cycle		2	0x0 (0b0)	Off (default)	
					0x1 (0b1)	Trigger	
ALS_INT		Enable / disable the interrupt function of the ALS channel		1	0x0 (0b0)	Disable (default)	
					0x1 (0b1)	Enable	
ALS_ON_0		Switch the sensor on / off (ALS_ON_0 and ALS_ON_1 must be executed together to start the sensor)		0	0x0 (0b0)	Turn on the sensor	
					0x1 (0b1)	Turn off the sensor (shutdown) (default)	

Note

- Command Code 0x00 default value is 0x01 = device shutdown

TABLE 4 - REGISTER NAME: ALS_CONF_1

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ALS_ON_1	ALS_PDDIV	Reserved	ALS_GAIN		ALS_PERS		ALS_CAL
COMMAND CODE					0x01		
BIT NAME		FUNCTION		BIT	VALUE	DESCRIPTION	
ALS_ON_1		Switch the sensor on / off (ALS_ON_0 and ALS_ON_1 must be executed together to start the sensor)		7	0x0 (0b0)	Turn on the sensor	
					0x1 (0b1)	Turn off the sensor (shutdown) (default)	
ALS_PDDIV		Set the effective photodiode size for the ALS and IR channel		6	0x0 (0b0)	4/4 PD used	
					0x1 (0b1)	1/4 PD used	
Reserved		Reserved		5	0x0 (0b0)	Should be kept default	
ALS_GAIN		Set the gain of the ALS		4 : 3	0x0 (0b00)	Gain x1	
					0x1 (0b01)	Gain x2	
					0x2 (0b10)	Gain x0.66	
					0x3 (0b11)	Gain x0.5	
ALS_PERS		Set the amount of consecutive threshold crossing events necessary to trigger interrupt		2 : 1	0x1 (0b00)	1 time (default)	
					0x2 (0b01)	2 times	
					0x3 (0b10)	4 times	
					0x4 (0b11)	8 times	
ALS_CAL		Internal calibration after power on		0	0x1 (0b1)	Must be set to “1” when power on ready	
					0x0 (0b0)	Disable (default)	

**TABLE 5 - REGISTER NAME: ALS_THDH**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ALS_THDH_L							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ALS_THDH_H							
COMMAND	BIT NAME	FUNCTION	BIT	VALUE	DESCRIPTION		
0x04	ALS_THDH_L	Set the high threshold interrupt value	7 : 0	0 to 65 535	Low byte		
0x05	ALS_THDH_H		7 : 0		High byte		

TABLE 6 - REGISTER NAME: ALS_THDL

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ALS_THDL_L							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ALS_THDL_H							
COMMAND	BIT NAME	FUNCTION	BIT	VALUE	DESCRIPTION		
0x06	ALS_THDL_L	Set the low threshold interrupt value	7 : 0	0 to 65 535	Low byte		
0x07	ALS_THDL_H		7 : 0		High byte		

TABLE 7 - REGISTER NAME: ALS_DATA

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ALS_DATA_L							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
ALS_DATA_H							
COMMAND	BIT NAME	FUNCTION	BIT	VALUE	DESCRIPTION		
0x10	ALS_DATA_L	Read the ALS channel output data	7 : 0	0 to 65 535	Low byte		
0x11	ALS_DATA_H		7 : 0		High byte		

TABLE 8 - REGISTER NAME: IR_DATA

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
IR_DATA_L							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
IR_DATA_H							
COMMAND	BIT NAME	FUNCTION	BIT	VALUE	DESCRIPTION		
0x12	IR_DATA_L	Read the IR channel output data	7 : 0	0 to 65 535	Low byte		
0x13	IR_DATA_H		7 : 0		High byte		

TABLE 9 - REGISTER NAME: VEML4031X00_ID

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VEML4031X00_ID_L							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
VEML4031X00_ID_H							
COMMAND	BIT NAME	FUNCTION		BIT	VALUE	DESCRIPTION	
0x14	VEML4031X00_ID_L	Read the device ID		7 : 0	0x01 (0b00000001)	Should be kept default	
0x15	VEML4031X00_ID_H			7 : 0	0x00 (0b00000000)	Device with a slave address of 0x29	
					0x10 (0b00010000)	Device with a slave address of 0x10	

**TABLE 10 - REGISTER NAME: INT_FLAG**

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Reserved							
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Reserved				AF_DATA_READY	ALS_IF_L	ALS_IF_H	Reserved
COMMAND	BIT NAME	FUNCTION	BIT	VALUE	DESCRIPTION		
0x16	Reserved	Reserved	7 : 0	0x00 (0b00000000)	Should be kept default		
	Reserved	Reserved	7 : 4	0x0 (0b0000)	Should be kept default		
	AF_DATA_READY	Data ready flag active force mode	3	0x1 (0b1)	Data ready flag available		
				0x0 (0b0)	Data ready flag not available		
	ALS_IF_L	Low threshold interrupt flag	2	0x1 (0b1)	Low threshold crossing interrupt event flag for the ALS channel		
				0x0 (0b0)	No low threshold crossing		
	ALS_IF_H	High threshold interrupt flag	1	0x1 (0b1)	High threshold crossing interrupt event flag for the ALS channel		
				0x0 (0b0)	No high threshold crossing		
	Reserved	Reserved	0	0x0 (0b0)	Should be kept default		

CALCULATING THE LUX LEVEL

Command code 0x10 and 0x11 contain the results of the ambient light channel measurement. The value of the ALS channel can be used to calculate the corresponding illumination. Therefore, the 16-bit code needs to be

converted to a decimal value to determine the corresponding lux value. The calculation of the corresponding lux level is dependent on the programmed gain setting and the chosen integration time.

TABLE 11 - RESOLUTION AND MAXIMUM DETECTION RANGE AT ALS_PDDIV (4/4 PD used)

	TYPICAL RESOLUTION (lx/cnt)					MAXIMUM POSSIBLE ILLUMINATION (lx)			
	ALS_GAIN					ALS_GAIN			
IT (ms)	x 2	x 1	x 0.66	x 0.5		x 2	x 1	x 0.66	x 0.5
400	0.0026	0.0051	0.0078	0.0103		168	337	510	673
200	0.0051	0.0103	0.0156	0.0205		337	673	1020	1346
100	0.0103	0.0205	0.0311	0.0411		673	1346	2040	2693
50	0.0205	0.0411	0.0623	0.0822		1346	2693	4080	5385
25	0.0411	0.0822	0.1245	0.1644		2693	5385	8160	10 771
12.5	0.0822	0.1644	0.2490	0.3287		5385	10 771	16 319	21 542
6.25	0.1644	0.3287	0.4980	0.6574		10 771	21 542	32 639	43 083
3.125	0.3287	0.6574	0.9961	1.3148	(-) ⁽¹⁾	(-) ⁽¹⁾	(-) ⁽¹⁾	(-) ⁽¹⁾	

TABLE 12 - RESOLUTION AND MAXIMUM DETECTION RANGE AT ALS_PDDIV (1/4 PD used)

	TYPICAL RESOLUTION (lx/cnt)					MAXIMUM POSSIBLE ILLUMINATION (lx)			
	ALS_GAIN					ALS_GAIN			
IT (ms)	x 2	x 1	x 0.66	x 0.5		x 2	x 1	x 0.66	x 0.5
400	0.0103	0.0205	0.0311	0.0411	673	1346	2040	2693	
200	0.0205	0.0411	0.0623	0.0822	1346	2693	4080	5385	
100	0.0411	0.0822	0.1245	0.1644	2693	5385	8160	10 771	
50	0.0822	0.1644	0.2490	0.3287	5385	10 771	16 319	21 542	
25	0.1644	0.3287	0.4980	0.6574	10 771	21 542	32 639	43 083	
12.5	0.3287	0.6574	0.9961	1.3148	21 542	43 083	65 278	86 166	
6.25	0.6574	1.3148	1.9921	2.6296	43 083	86 166	130 555	172 333	
3.125	1.3148	2.6296	3.9843	5.2593	(-) ⁽¹⁾	(-) ⁽¹⁾	(-) ⁽¹⁾	(-) ⁽¹⁾	

Note

⁽¹⁾ For integration time of 3.125 ms the maximum count level is no longer 16 bit, so, half the integration time no longer leads to double the max. lux level



HANDLING INSTRUCTION

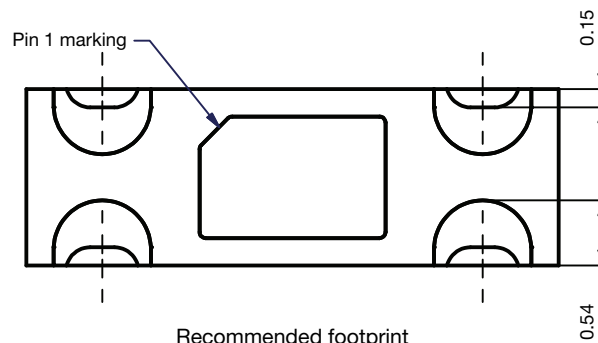
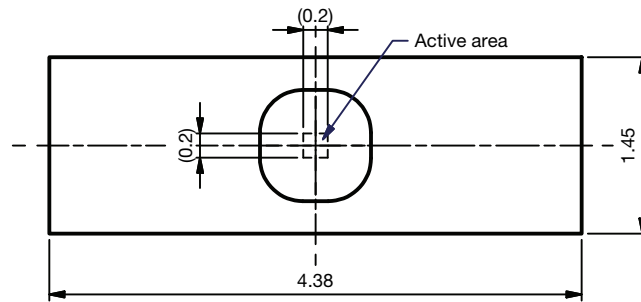
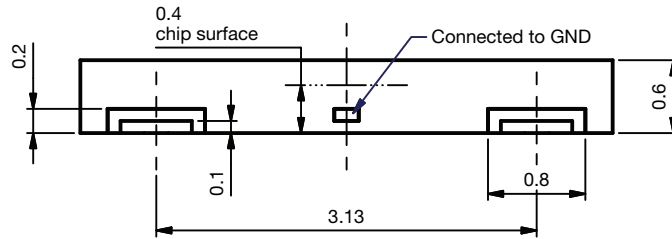
Special care must be taken into consideration when handling the VEML4031X00. The VEML4031X00 is sensitive to dust and scratches, proper optical device handling procedures are recommended.

The optical surface of the device must be kept clean for optimal performance in both prototyping with the device and mass production manufacturing procedures. Tweezers with plastic or rubber contact surfaces are recommended to avoid scratches on the optical surface. Avoid manipulation with metal tools when possible. The optical surface must be kept clean of fingerprints, dust, and other optical-inhibiting contaminants.

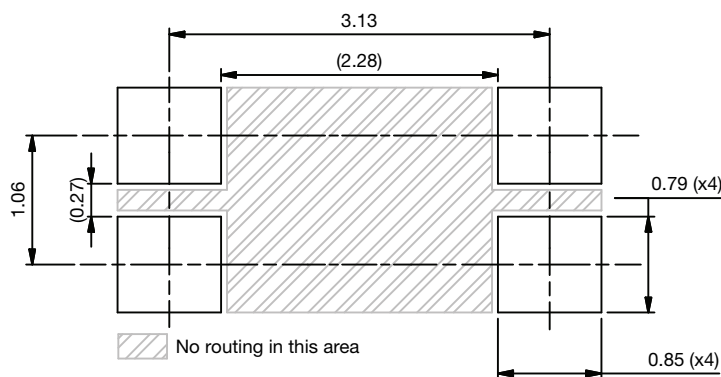
If the device optical surface requires cleaning, the use of isopropyl alcohol is recommended. A few gentle brushes with a soft swab are appropriate. Avoid potentially abrasive cleaning and manipulating tools and excessive force that can scratch the optical surface.

If the VEML4031X00 performs less than optimally, inspect the optical surface for dirt, scratches, or other optical artifacts.

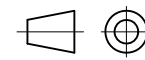
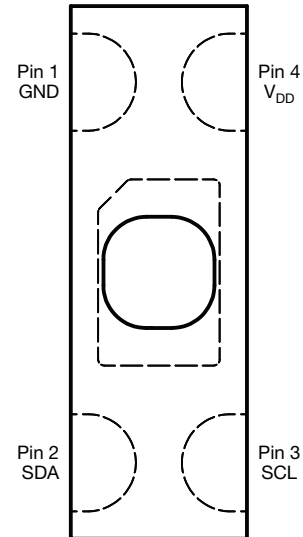
The VEML4031X00 is a cost effective solution of ambient light sensor with I²C bus interface. The standard serial digital interface is easy to access "Ambient Light Signal" without complex calculation and programming by external controller. Beside the digital output also a flexible programmable interrupt pin is available.

PACKAGE DIMENSIONS in millimeters


Recommended footprint

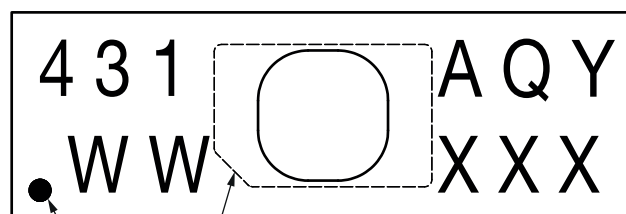


Pinning top view


Technical drawings
according to DIN
specification

All dimensions in mm incl. burrs
Not indicated tolerances ± 0.1

Drawing No.: 6.550-5388.01
Issue: 1; 04.06.2024

MARKING AND PIN 1 IDENTIFICATION

Pin 1 marking
dotmarking on top side
chamfer on center pad on bottom side

431: device type
A: address option (0, 1, 2, etc.)
0: qualification (0 = AEC-Q100)

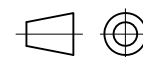
Y: year
WW: week
XXX: lot number

TAPE AND REEL DIMENSIONS in millimeters

Reel size:

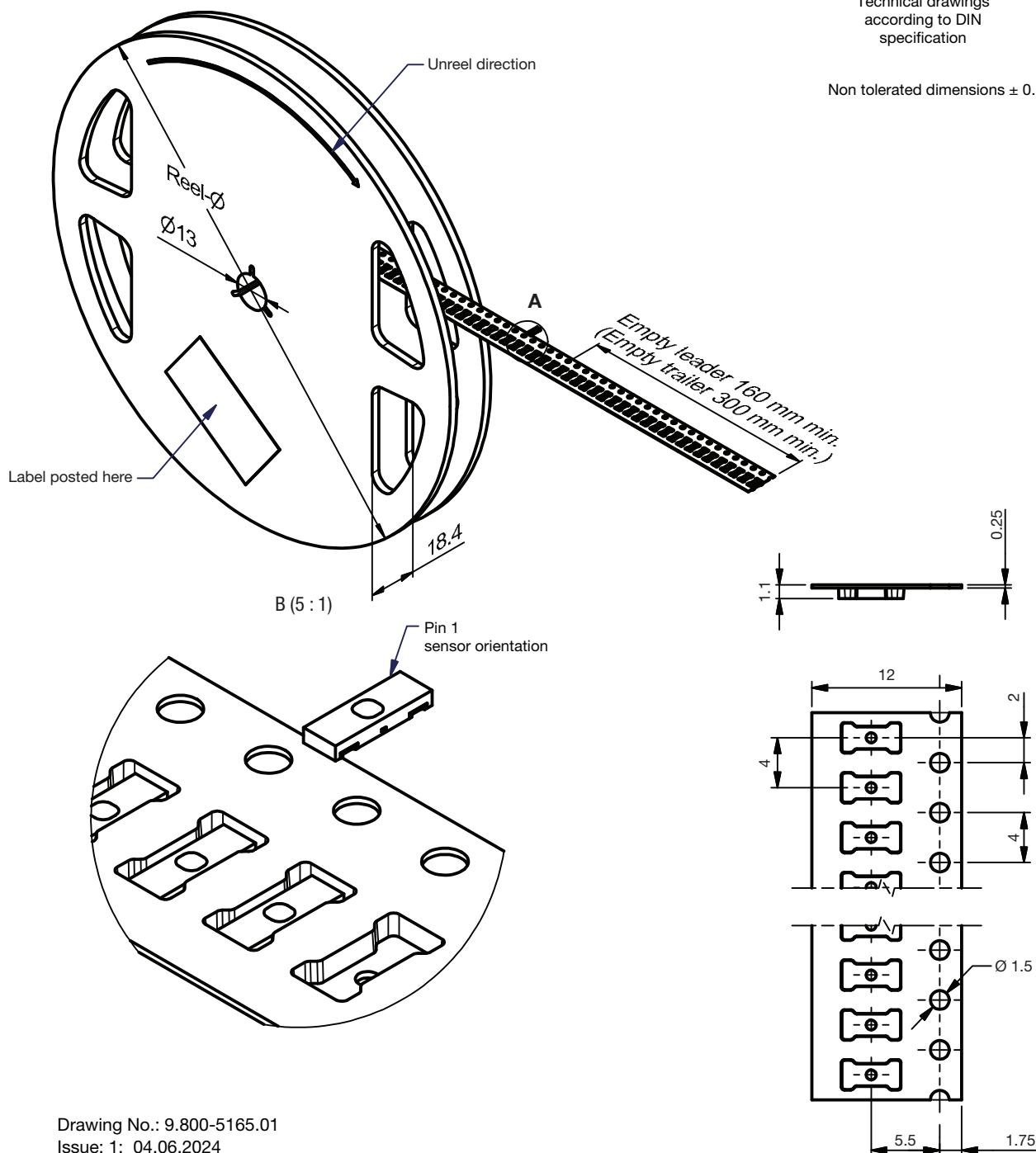
VEML40xx: Ø 180 mm ± 2 mm = 4500 pcs.

Reel design is representative for different types.



Technical drawings
according to DIN
specification

Non tolerated dimensions ± 0.1 mm



Drawing No.: 9.800-5165.01
Issue: 1; 04.06.2024



DRYPACK

Devices are packed in moisture barrier bags (MBB) to prevent the products from moisture absorption during transportation and storage. Each bag contains a desiccant.

FLOOR LIFE

Floor life (time between soldering and removing from MBB) must not exceed the time indicated on MBB label:

Floor life: 4 weeks

Conditions: $T_{amb} < 30\text{ }^{\circ}\text{C}$, RH < 60 %

Moisture sensitivity level 2a, according to J-STD-020.

DRYING

In case of moisture absorption devices should be baked before soldering. Conditions see J-STD-020 or label. Devices taped on reel dry using recommended conditions 192 h at $40\text{ }^{\circ}\text{C}$ (+ $5\text{ }^{\circ}\text{C}$), RH < 5 %.

REFLOW SOLDER PROFILE

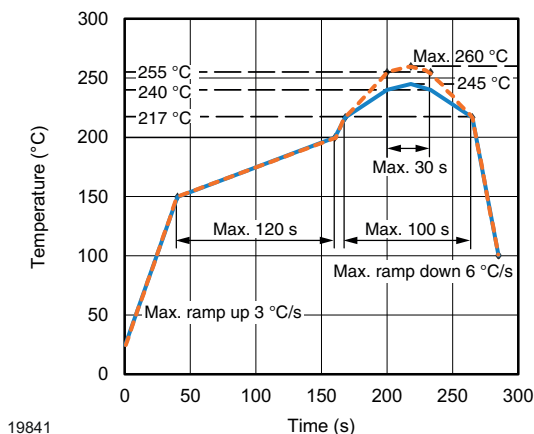


Fig. 12 - Lead (Pb)-free Reflow Solder Profile According to J-STD-020



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